
Univariate (and multivariate) extreme value theory

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Course details

- Supplementary material (if any) can be downloaded from

`http://mribatet.perso.math.cnrs.fr/teaching.html`

- Grading: Written exam

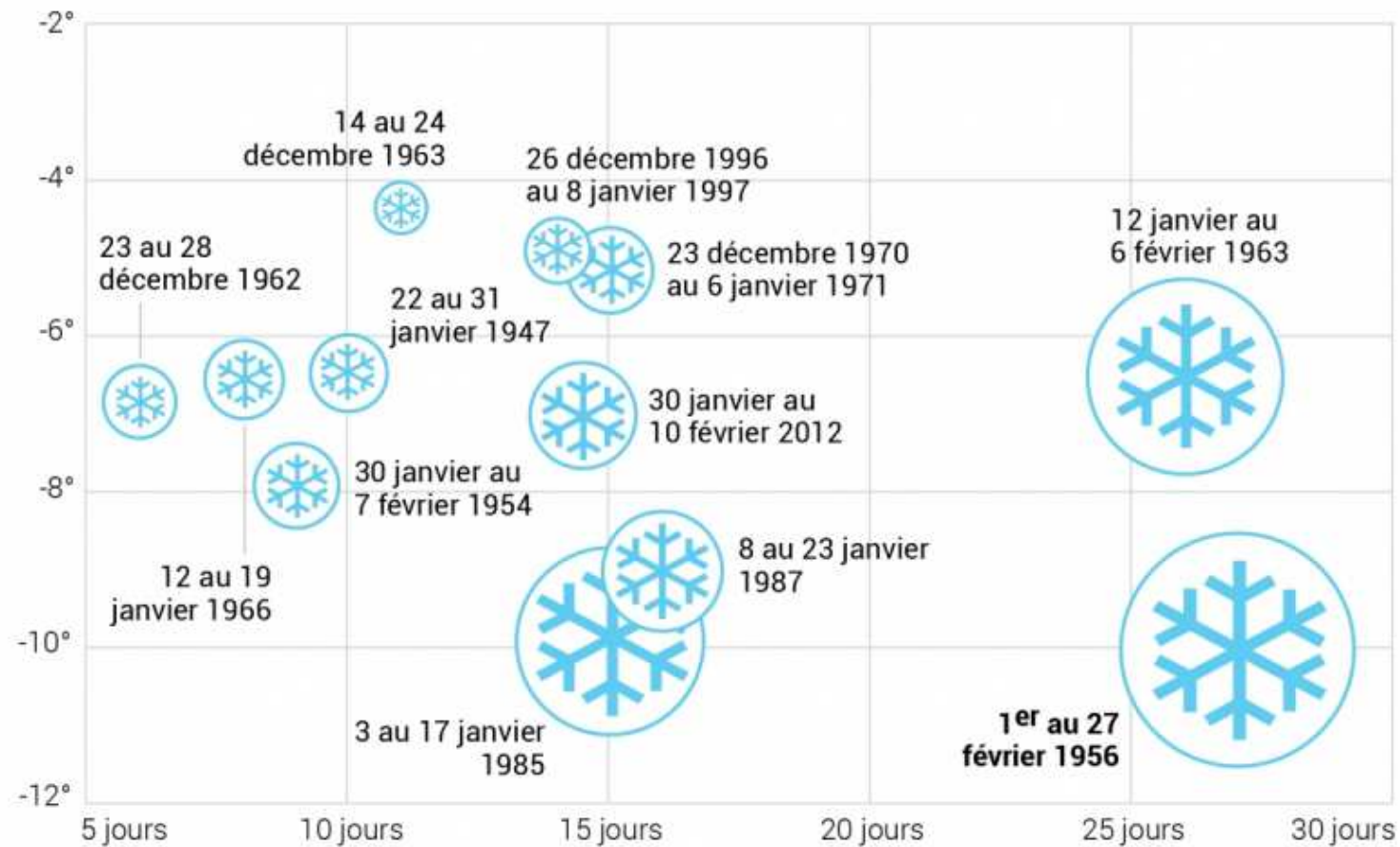
Bibliography

- Coles (2001) An Introduction to Statistical Modeling of Extreme Values, Springer
- de Haan and Ferreira (2006) Extreme Value Theory: An Introduction, Springer
- Resnick (1987) Extreme values, Regular variation and Point processes, Springer
- Embrechts, Klüppelberg and Mikosch (1997) Modelling Extreme Events for Insurance and Finance, Springer

Les plus grandes vagues de froid depuis 1947

○ Le diamètre des sphères symbolise l'intensité globale des vagues de froid

Température (°C)



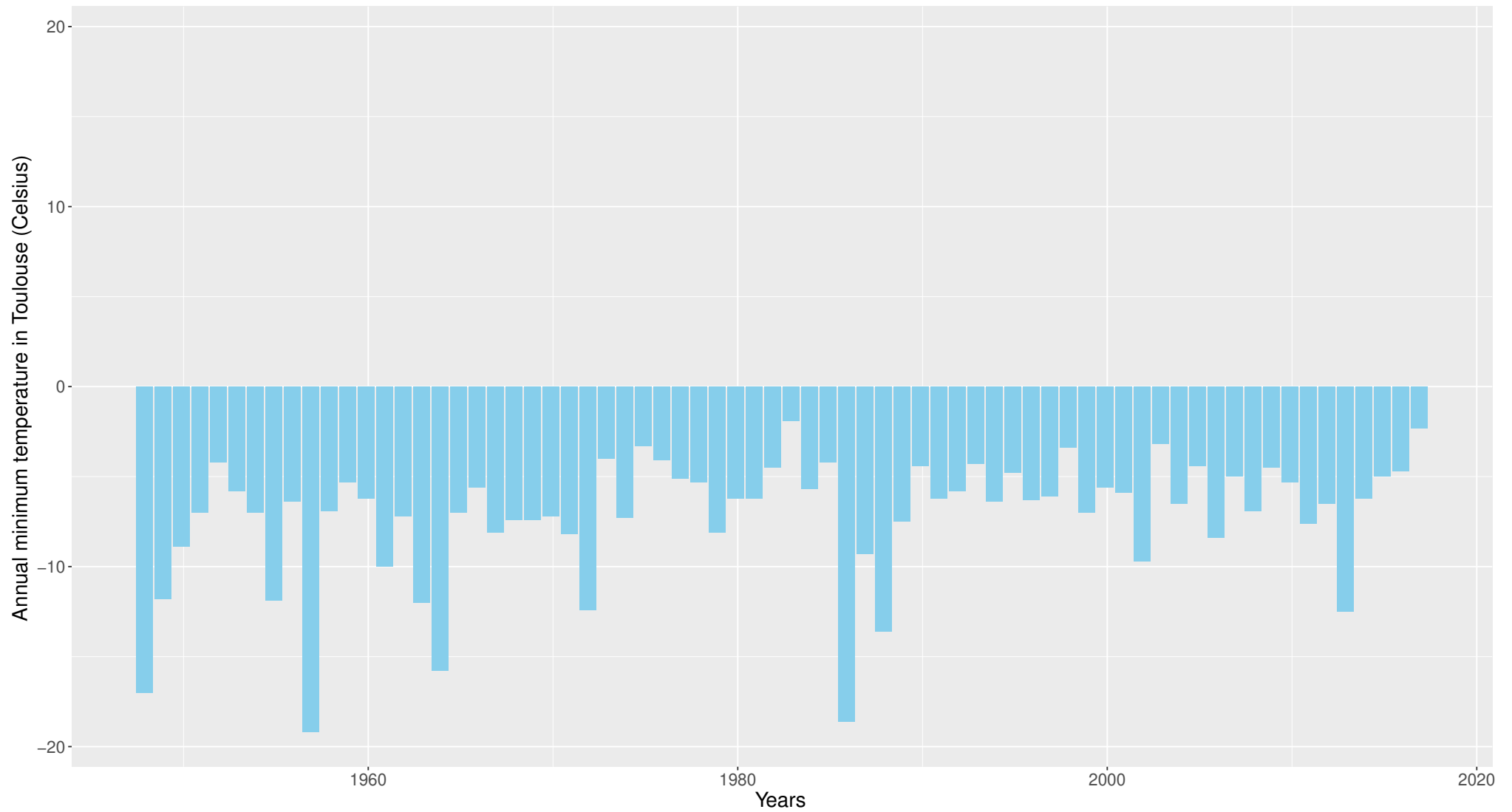
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Environmental extremes



Environmental extremes



Environmental extremes (2)

Knowledge of the distribution of environmental extremes might be useful for

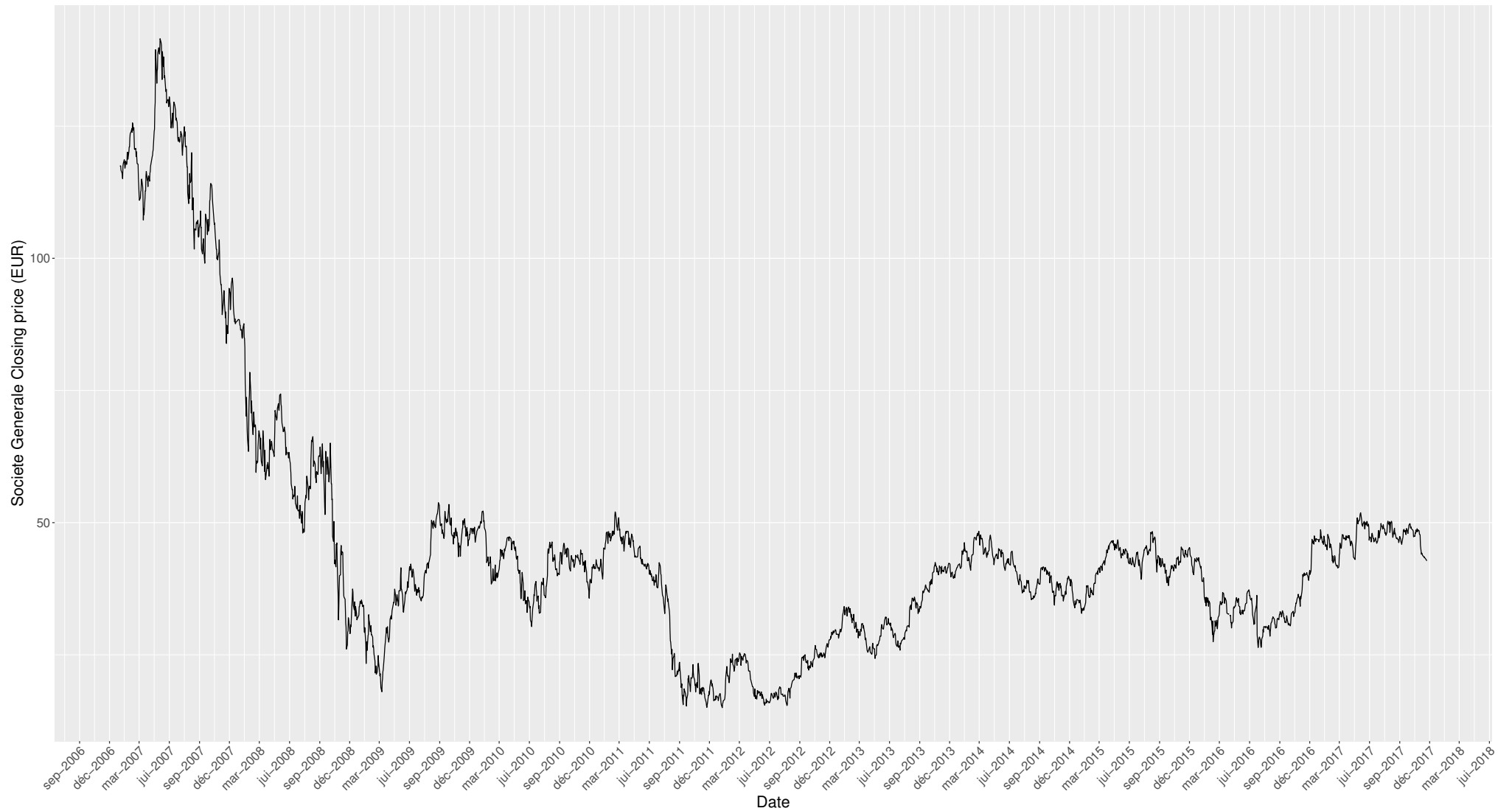
- economic reasons, prevent any severe damage due to a storm, extremely cold temperatures, ... yielding to economic losses;
- policy management to characterize the potential human losses if some extreme weather events occur—France 2003.



Financial extremes



Financial extremes



Financial extremes (2)

Knowledge of the distribution of financial extremes might be useful to

- be in agreement with the **Basel committee**, e.g., characterize the **value at risk**;
- assess to which extent a given company is “at risk”;
- derive optimal portfolio management such as extension of the Markowitz framework.

History

- 1930: Foundations of asymptotic arguments from Fisher and Tippett
- 1940s: Unification and extension of the asymptotic theory by Gnedenko and von Mises
- 1950s: First statistical modelling from asymptotic distribution by Gumbel and Jenkinson
- 1960s: Multivariate maxima
- 1970s: Threshold exceedances
- 1980s: Extremes for stationary processes, point processes approaches
- 1990s: Multivariate modelling strategies, Bayesian approaches
- 2000s: Softwares
- 2010s: Spatial extremes

▷ 1. Block maxima

Type and Max-stability

Extremal type theorem

The three limiting families

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1. Block maxima

Set up

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- Let $X_1, \dots, X_m \stackrel{\text{iid}}{\sim} F$ and define the (block) maximum $M_m = \max\{X_1, \dots, X_m\}$. Clearly we have

$$\begin{aligned}\Pr(M_m \leq x) &= \Pr(X_1 \leq x, \dots, X_m \leq x) \\ &= \Pr(X_1 \leq x) \times \dots \times \Pr(X_m \leq x) \\ &= F(x)^m.\end{aligned}$$

- F is unknown so approximate F^m with some relevant distribution.
- As $m \rightarrow \infty$ we have

$$F(x)^m \longrightarrow \begin{cases} 0, & F(x) < 1, \\ 1, & F(x) = 1, \end{cases}$$

so $M_m \xrightarrow{D} x_+$ where $x_+ = \sup\{x \in \mathbb{R} : F(x) < 1\}$. We say that the limiting distribution is **degenerate**.

How to avoid degenerate limiting distribution?

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- You already met degenerate distribution, e.g., provided $\mathbb{E}(|X|) < \infty$,

$$\bar{X}_m = \frac{1}{m} \sum_{i=1}^m X_i \xrightarrow{D} \mathbb{E}(X), \quad m \rightarrow \infty.$$

- Question: How would you get a non degenerate distribution?

How to avoid degenerate limiting distribution?

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$$\bar{X}_m = \frac{1}{m} \sum_{i=1}^m X_i \xrightarrow{D} \mathbb{E}(X), \quad m \rightarrow \infty.$$

- Question: How would you get a non degenerate distribution?

- We will just do the same with M_m !

Examples

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Example 1. Find suitable (normalizing) sequences such that maxima of independent random variables from the

- i) Exponential(1)
- ii) (unit) Fréchet, i.e., $\Pr(X \leq x) = \exp(-1/x)$, $x > 0$
- iii) Uniform(0,1)

distributions have non-degenerate limiting distributions.

Numerical illustration

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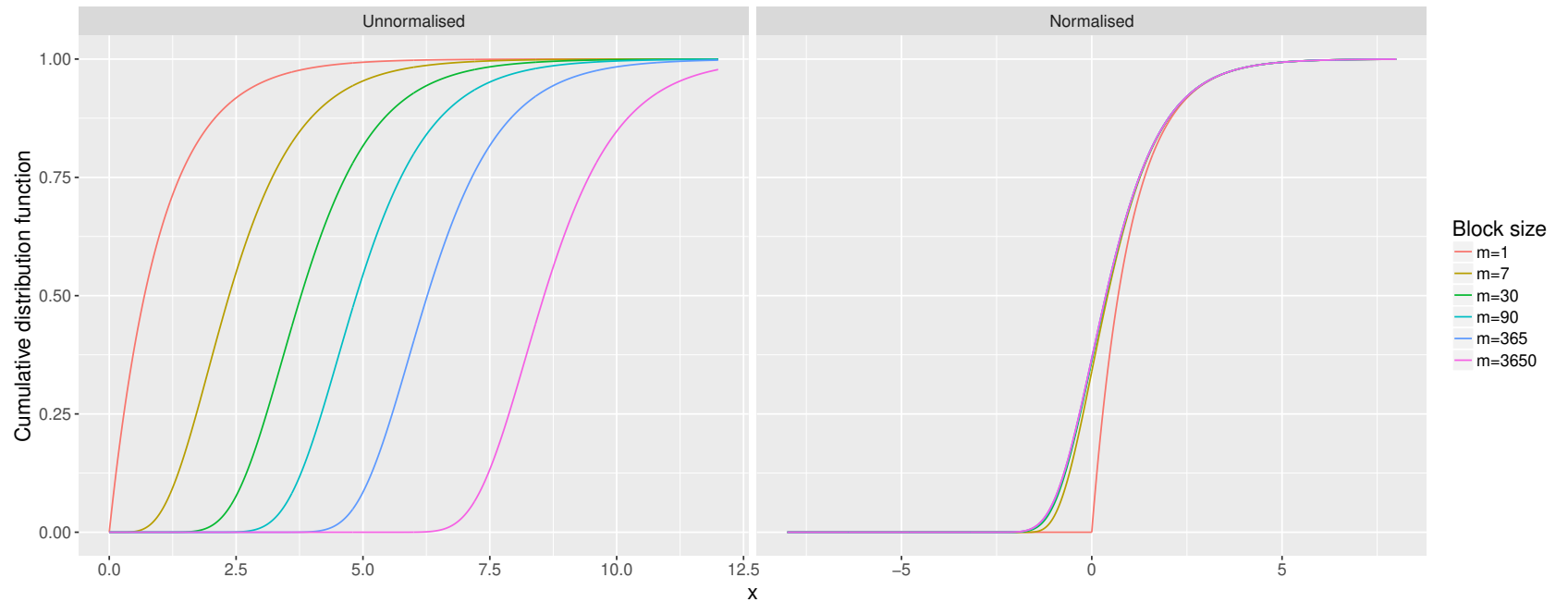


Figure 1: *Distribution of maxima (left) and normalized maxima (right) with $m = 1, 7, 30, 90, 365, 3650$ standard Exponential random variables.*

Type and Max-stability

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Definition 1. A distribution H is said to be **max-stable** if for any $k \in \mathbb{N}_*$

$$H^k(x) = H(a_k x + b_k),$$

for some constants a_k and b_k .

Definition 2. Two distributions F and G are of the **same type** if there are constants $a > 0$ and $b \in \mathbb{R}$ such that $G(ax + b) = F(x)$ for all $x \in \mathbb{R}$.

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Clearly if a limiting distribution H for normalized maxima exists, it must be max-stable since as $m \rightarrow \infty$

$$\Pr\left(\frac{M_{mk} - b_{mk}}{a_{mk}} \leq x\right) \longrightarrow H(x),$$

$$\Pr\left(\frac{M_m - b_m}{a_m} \times \frac{a_m}{a_{mk}} + \frac{b_m - b_{mk}}{a_{mk}} \leq x\right)^k \longrightarrow H\left\{\frac{x - \beta(k)}{\alpha(k)}\right\}^k,$$

as the convergence to types theorem states that

$$\frac{a_m}{a_{mk}} \longrightarrow \alpha(k) > 0, \quad \frac{b_m - b_{mk}}{a_{mk}} \longrightarrow \beta(k), \quad m \rightarrow \infty.$$

Extremal type theorem

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Theorem (Extremal types theorem). *If there exist sequences of constants $\{a_m > 0: m \geq 1\}$ and $\{b_m \in \mathbb{R}: m \geq 1\}$ such that, as $m \rightarrow \infty$,*

$$\Pr\left(\frac{M_m - b_m}{a_m} \leq x\right) \rightarrow H(x),$$

*for some non-degenerate distribution H , then H has the **same type** as one of the following distributions:*

I: $H(x) = \exp\{-\exp(-x)\}, x \in \mathbb{R};$

II: $H(x) = \begin{cases} 0, & x \leq 0, \\ \exp(-x^{-\alpha}), & x > 0, \alpha > 0; \end{cases}$

III: $H(x) = \begin{cases} \exp\{-(-x)^\alpha\}, & x < 0, \alpha > 0, \\ 1, & x \geq 0. \end{cases}$

The three limiting families

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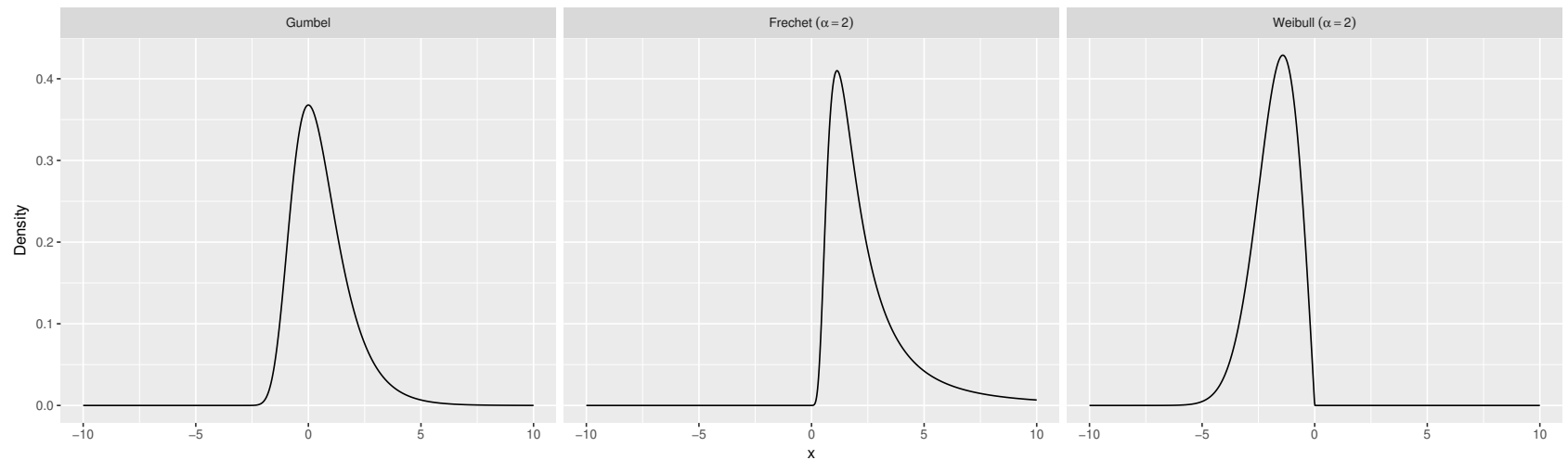
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- The three limiting distributions are known respectively as the **Gumbel**, **Fréchet** and **Weibull** distributions.
- Note that Fréchet is lower bounded, Weibull is upper bounded.

Statistical application

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- From a statistical perspective, we assume that for some (unknown) $a > 0$ and $b \in \mathbb{R}$,

$$\Pr\left(\frac{M_m - b}{a} \leq x\right) \approx H(x),$$

or in other words,

$$\Pr(M_m \leq x) \approx H\left(\frac{x - b}{a}\right) = H_2(x),$$

where H_2 is of the same type as H .

- We thus fit one of the three family to a series of observations of M_m .

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where H_2 is of the same type as H .

- We thus fit one of the three family to a series of observations of M_m .
- It is a bit unfortunate that we need to consider three different families...

The Generalized Extreme Value distribution

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Definition 3. A random variable X has a **Generalized Extreme Value** distribution $\text{GEV}(\mu, \sigma, \xi)$ if its c.d.f. is

$$H(x) = \exp \left\{ - \left(1 + \xi \frac{x - \mu}{\sigma} \right)^{-1/\xi} \right\}, \quad 1 + \xi \frac{x - \mu}{\sigma} > 0.$$

The GEV distribution has three parameters: a location $\mu \in \mathbb{R}$, a scale $\sigma > 0$ and a shape $\xi \in \mathbb{R}$.

The case $\xi = 0$ is derived by a continuity extension, i.e.,

$$H(x) = \exp \left\{ - \exp \left(- \frac{x - \mu}{\sigma} \right) \right\}, \quad x \in \mathbb{R}.$$

- The shape parameter controls the tail, i.e.,
 - $\xi > 0$ corresponds to the heavy-tailed (Fréchet) case;
 - $\xi = 0$ corresponds to the light-tailed (Gumbel) case;
 - $\xi < 0$ corresponds to the short-tailed (Weibull) case.

Extremal type theorem 2.0

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Theorem. *If there exist sequences of constants $\{a_m > 0: m \geq 1\}$ and $\{b_m \in \mathbb{R}: m \geq 1\}$ such that, as $m \rightarrow \infty$,*

$$\Pr\left(\frac{M_m - b_m}{a_m} \leq x\right) \rightarrow H(x),$$

for some non-degenerate distribution H , then

$$H(x) = \exp\left\{-\left(1 + \xi \frac{x - \mu}{\sigma}\right)^{-1/\xi}\right\}, \quad 1 + \xi \frac{x - \mu}{\sigma} > 0,$$

for some $\mu \in \mathbb{R}$, $\sigma > 0$ and $\xi \in \mathbb{R}$.

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Theorem. *If there exist sequences of constants $\{a_m > 0: m \geq 1\}$ and $\{b_m \in \mathbb{R}: m \geq 1\}$ such that, as $m \rightarrow \infty$,*

$$\Pr\left(\frac{M_m - b_m}{a_m} \leq x\right) \longrightarrow H(x),$$

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$$H(x) = \exp\left\{-\left(1 + \xi \frac{x - \mu}{\sigma}\right)^{-1/\xi}\right\}, \quad 1 + \xi \frac{x - \mu}{\sigma} > 0,$$

for some $\mu \in \mathbb{R}$, $\sigma > 0$ and $\xi \in \mathbb{R}$.

Remark. Watch out! The theorem above states that **if the limit exists** it has to be GEV. In general there is no guarantee that such a limit exists, e.g., Poisson distribution.

Domains of attraction

Definition 4. A distribution F is said to belong to the **(max) domain of attraction** of
Gumbel
the Fréchet distribution if the limiting distribution of $\frac{M_m - b_m}{a_m}$ is Fréchet
Weibull Weibull

Example 2. The (max) domain of attraction of the Normal distribution is Gumbel.

- In practice the notion of domain of attraction is of little interest since typically F is unknown—and so is the domain of attraction!

von Mises conditions

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- How one can determine sequences $\{a_m : m \geq 1\}$ and $\{b_m : m \geq 1\}$?
- The **von Mises conditions** give sufficient (but not necessary) simple conditions, i.e., for a (smooth enough) distribution F the **Mills ratio** is

$$r(x) = \frac{1 - F(x)}{f(x)}.$$

Then with

$$b_m = F^{-1}\left(1 - \frac{1}{m}\right), \quad a_m = r(b_m), \quad \xi = \lim_{x \rightarrow x_+} r'(x),$$

the limit distribution of $(M_m - b_m)/a_m$ is GEV with shape ξ .

Example 3. Use the von Mises conditions to check the limiting distribution of maxima from the uniform, exponential, Fréchet and Gaussian distribution.

Penultimate approximation

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- Convergence to the limiting distribution may be slow.
- Taking $\xi_m = r'(b_m)$ may give better approximation to the distribution of $(M_m - b_m)/a_m$ for finite m than does using the limiting approximation.

Example 4. For the $N(0, 1)$ case we have

$$\xi_7 \approx -0.324, \quad \xi_{30} \approx -0.176, \quad \xi_{90} \approx -0.13, \quad \xi_{365} \approx -0.097, \quad \xi_{3650} \approx -0.068,$$

so the distribution of M_m is short-tailed compared to the Gumbel limit—even when m is very large!

Penultimate approximation

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so the distribution of M_m is short-tailed compared to the Gumbel limit—even when m is very large!

- As a consequence, even if we were sure about the Gumbel limit, one should prefer fitting a GEV with an arbitrary shape parameter ξ .

Illustration of the penultimate approximation

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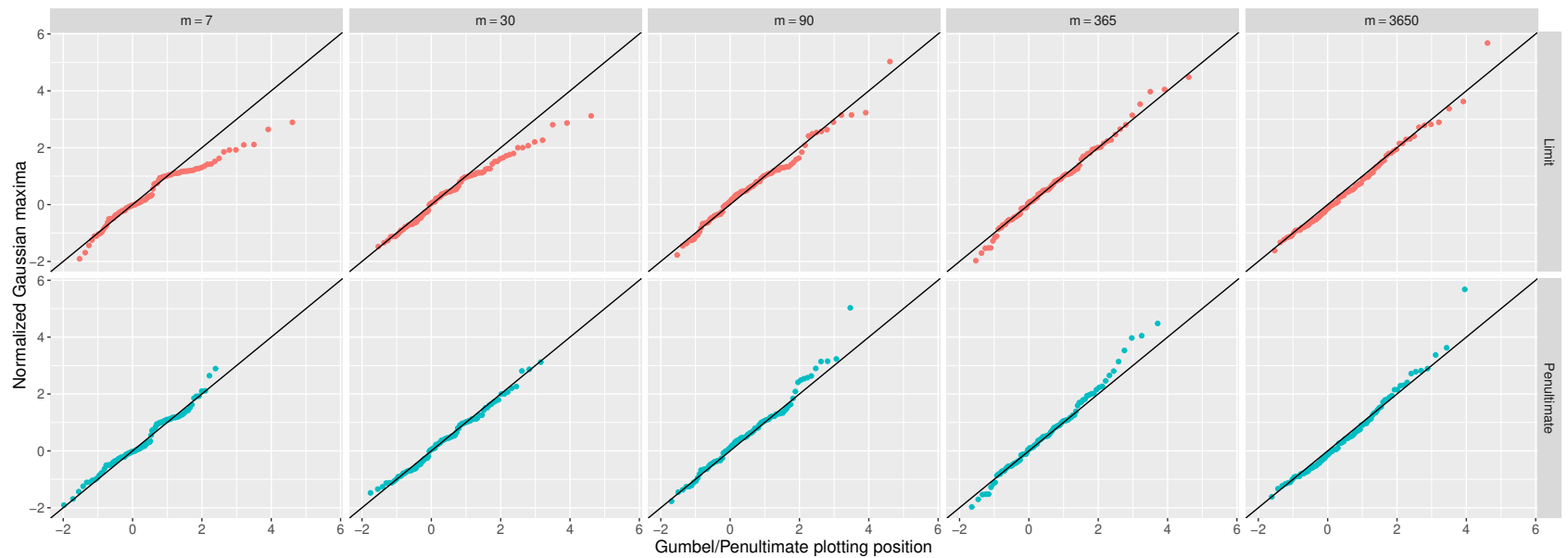


Figure 2: Illustration of the penultimate approximation with 100 replicated of renormalized $N(0,1)$ maxima with $m = 7, 30, 90, 365, 3650$.

Recall the extremal types theorem

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$$\Pr\left(\frac{M_m - b_m}{a_m} \leq x\right) \rightarrow H(x),$$

for some non-degenerate distribution H , then

$$H(x) = \exp\left\{-\left(1 + \xi \frac{x - \mu}{\sigma}\right)^{-1/\xi}\right\}, \quad 1 + \xi \frac{x - \mu}{\sigma} > 0,$$

for some $\mu \in \mathbb{R}$, $\sigma > 0$ and $\xi \in \mathbb{R}$.

Statistical interpretation

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- We observe a time series of, say, daily values X_1, X_2, \dots supposed to be independent and identically distributed from F
- We compute the maxima $M_m = \max(X_1, \dots, X_m)$ of blocks of the original time series
 - Environmental applications: annual maxima with $m = 365$, monthly maxima $m = 30$
 - Finance: annual maxima with $m = 250$, monthly maxima $m = 20$
- We suppose that this new time series of block maxima follows the GEV distribution with unknown parameters μ, σ and ξ .
- We then estimate the parameters and use our fitted GEV for estimations.

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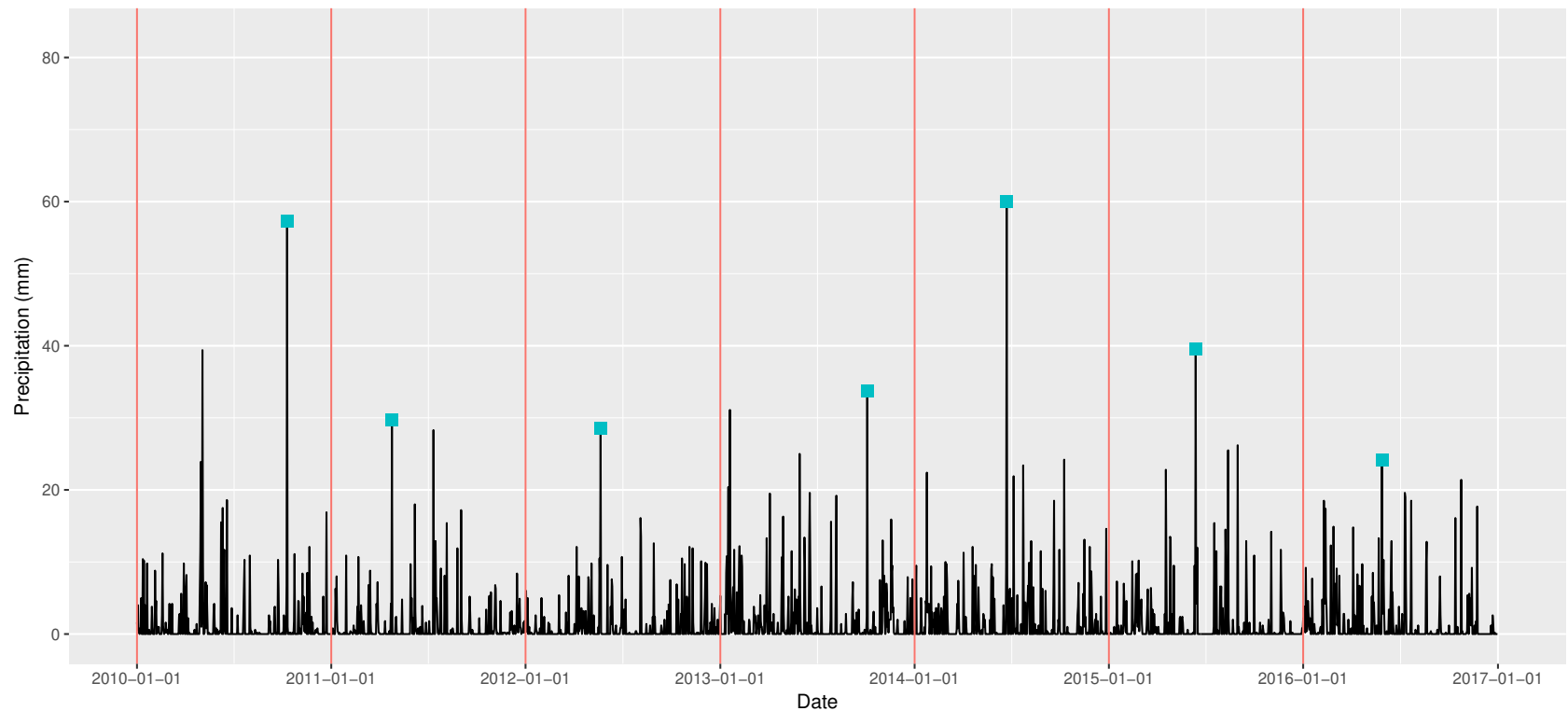


Figure 3: *Annual maxima for precipitation (mm) recorded at Toulouse-Blagnac.*

- Watch out for seasonality, starting/ending of blocks, e.g., hydrological years.

Financial applications

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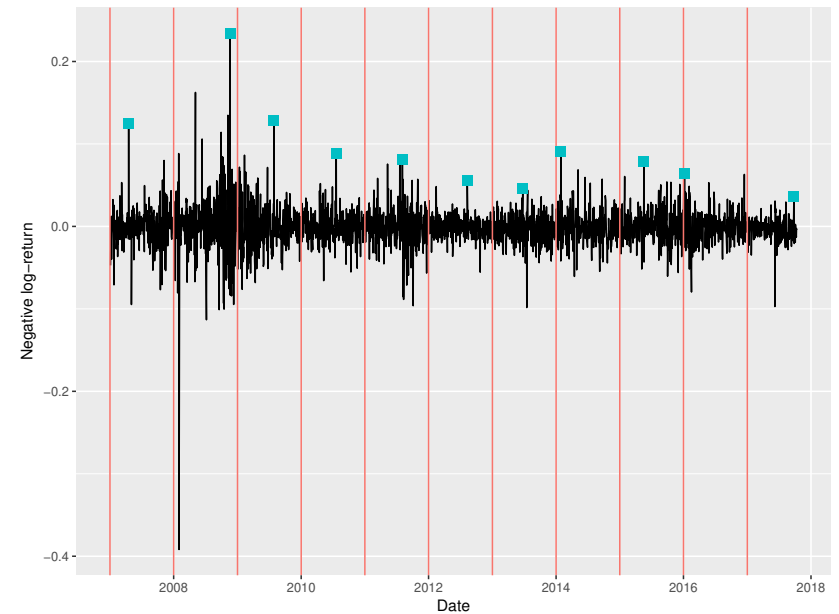


Figure 4: Illustration about the use of (negative) log-returns, i.e., $Y_t = -\log(X_t/X_{t-1})$ —Yahoo closing prices.

- It is common practice to work on the (negative) log-return to cancel out trends and mitigate the volatility.

Quantiles for the GEV

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- Let $p \in (0, 1)$, the quantile y_p of a $\text{GEV}(\mu, \sigma, \xi)$ with **exceedance probability** p , i.e., $F(y_p) = 1 - p$, is

$$y_p = \mu - \sigma \frac{1 - \{-\log(1 - p)\}^{-\xi}}{\xi}.$$

- In environmental application we say that y_p is the **return level** associated with the **return period** $1/p$.
- In finance we say that y_p is the **Value at Risk (VaR)**.
- In both cases, y_p is a quantile.

Why the phrasing “return period”?

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- Let $T = 1/p$ with $p \in (0, 1)$.
- Let $Y_1, Y_2, \dots \stackrel{\text{iid}}{\sim} Y$ and consider the random variable

$$I = \operatorname{argmin} \{i \geq 1 : Y_i \geq y_p\}, \quad \Pr(Y \geq y_p) = p.$$

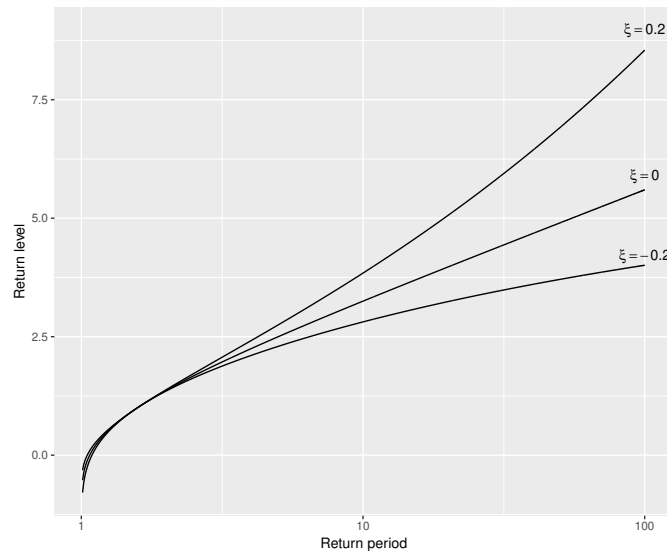
- Clearly $I \sim \operatorname{Geom}(p)$ as $\Pr(\text{“success”}) = \Pr(Y \geq y_p) = p$.
- Hence $\mathbb{E}(I) = 1/p = T$, that is, y_p is expected to be exceeded once every $T = 1/p$ observations.
- If the Y_i 's are block maxima, it is expected to be exceeded once every $T = 1/p$ blocks, e.g., years.

Remark. Don't be fooled! It doesn't refer to any kind of periodicity...

Return level plot

It is common practice to show results using a **return level plot**, i.e., plotting on a log-scale for the x -axis the function

$$f: T \mapsto y_p = \mu - \sigma \frac{1 - \{-\log(1 - p)\}^{-\xi}}{\xi}, \quad p = \frac{1}{T}.$$

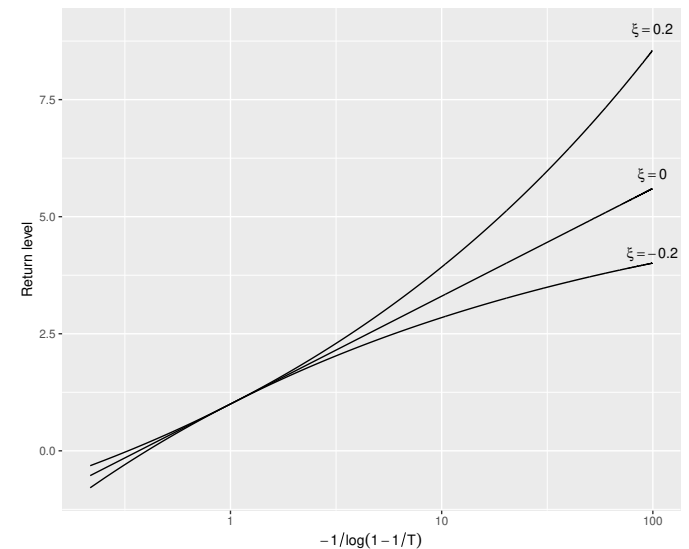
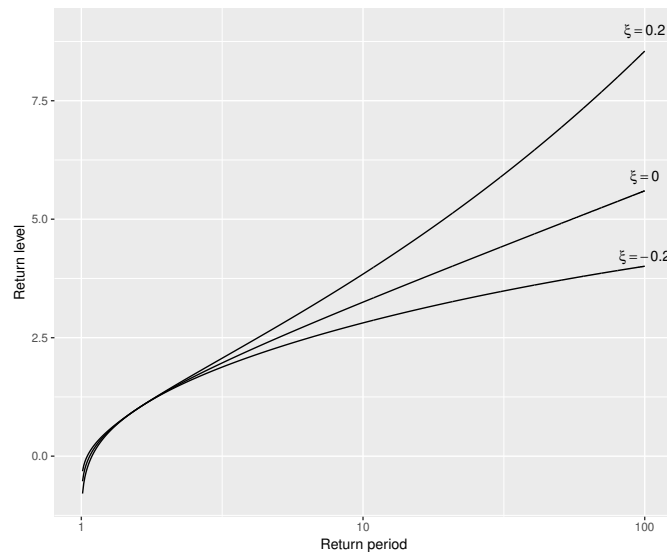


- 1. Block maxima
- Type and Max-stability
- Extremal type theorem
- The three limiting families
- GEV
- Domains of attraction
- von Mises conditions
- Penultimate approximation
- Quantile
- ▷ Return level plot
- Inference
- Model checking
- Assessing uncertainties
- 2. Threshold exceedances
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences

Return level plot

It is common practice to show results using a **return level plot**, i.e., plotting on a log-scale for the x -axis the function

$$f: T \mapsto y_p = \mu - \sigma \frac{1 - \{-\log(1 - p)\}^{-\xi}}{\xi}, \quad p = \frac{1}{T}.$$



Remark. Sometimes the x -axis is not the return period T but rather $-1/\log(1 - 1/T)$. Since $-1/\log(1 - 1/T) \sim T$ as $T \sim \infty$, both plots are roughly the same.

- 1. Block maxima
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1. Block maxima

Type and Max-stability

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Given observed block maxima Y_1, \dots, Y_n , we want to estimate the GEV parameters (μ, σ, ξ) . One could use

- moment based estimators—usually not relevant as moments might not exist with extremes.
- probability weighted moments—good small sample performance but not very flexible.
- likelihood based approaches (by far the most used approach)
 - flexible and usually efficient;
 - model selection is easy (AIC, BIC, Likelihood ratio, ...)
 - can be embedded, if necessary, into a Bayesian framework.

Example: Precipitation extremes at Toulouse–Blagnac

1. Block maxima

Type and Max-stability

Extremal type theorem

The three limiting families

GEV

Domains of attraction

von Mises conditions

Penultimate approximation

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5. Stationary sequences

```
> library(evd)##R package for EVT (other alternatives exist)
> head(data)##data is an R matrix giving the *raw* data
  Years Precip
1  1947    0.2
2  1947    0.2
3  1947    0.0
4  1947    0.0
5  1947    6.0
6  1947    0.4
> block.max <- aggregate(Precip~Years, FUN = max, data = data)
> (fitted <- fgev(block.max[, "Precip"]))
```

```
Call: fgev(x = block.max[, "Precip"])
Deviance: 543.5806
```

Estimates

	loc	scale	shape
	35.12564	9.90881	0.01489

Standard Errors

	loc	scale	shape
	1.33591	0.97678	0.09087

...

Model checking: QQ-plot

1. Block maxima

Type and Max-stability

Extremal type theorem

The three limiting families

GEV

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- QQ-plots are useful for model checking, identifying possible outliers
- Given a sample $Y_1, \dots, Y_n \stackrel{\text{iid}}{\sim} F$ we plot the **order statistics** $Y_{(1)} < \dots < Y_{(n)}$ against the **plotting positions** of F , e.g., the fitted GEV,

$$F^{-1}\left(\frac{1}{n+1}\right) < \dots < F^{-1}\left(\frac{n}{n+1}\right).$$

- If F is a sensible statistical model, one should get a points lying close to a straight line of unit slope through the origin.

QQ-plot: Toulouse-Blagnac

1. Block maxima

Type and Max-stability

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▷ Model checking

Assessing uncertainties

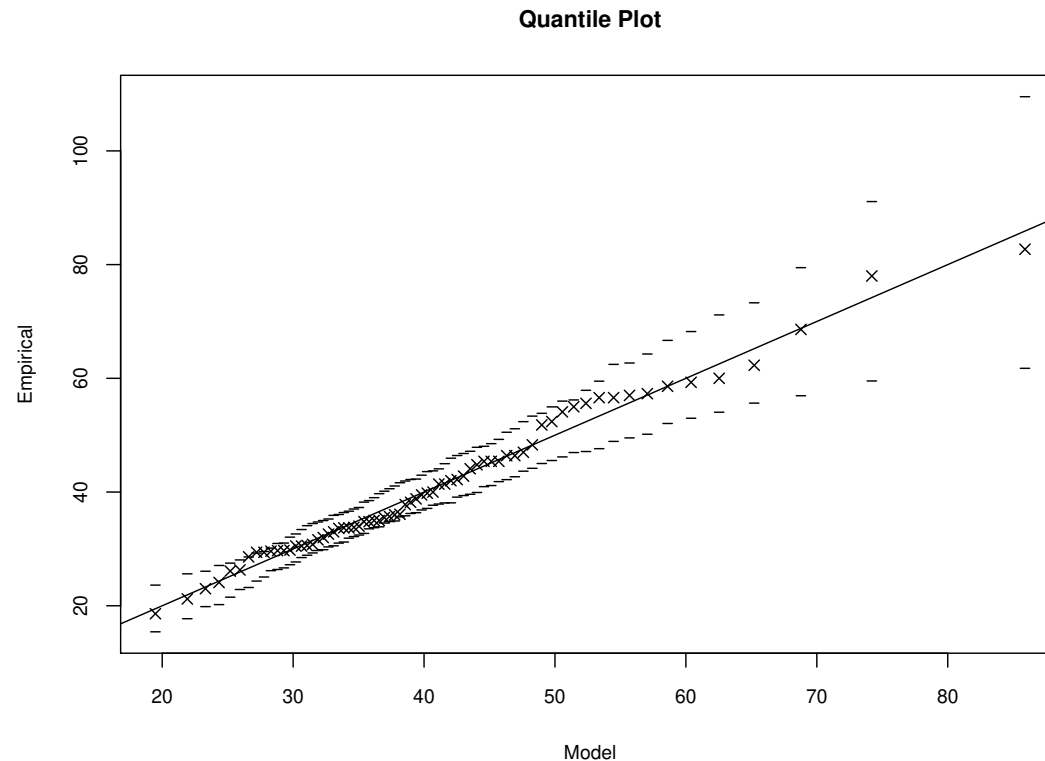
2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

```
> qq(fitted)
```



Remark. The plot shows **95% pointwise confidence intervals** obtained by parametric bootstrap.

Return level plot: Toulouse–Blagnac

```
> rl(fitted)
```

1. Block maxima

Type and Max-stability

Extremal type theorem

The three limiting families

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Domains of attraction

von Mises conditions

Penultimate approximation

Quantile

Return level plot

Inference

▷ Model checking

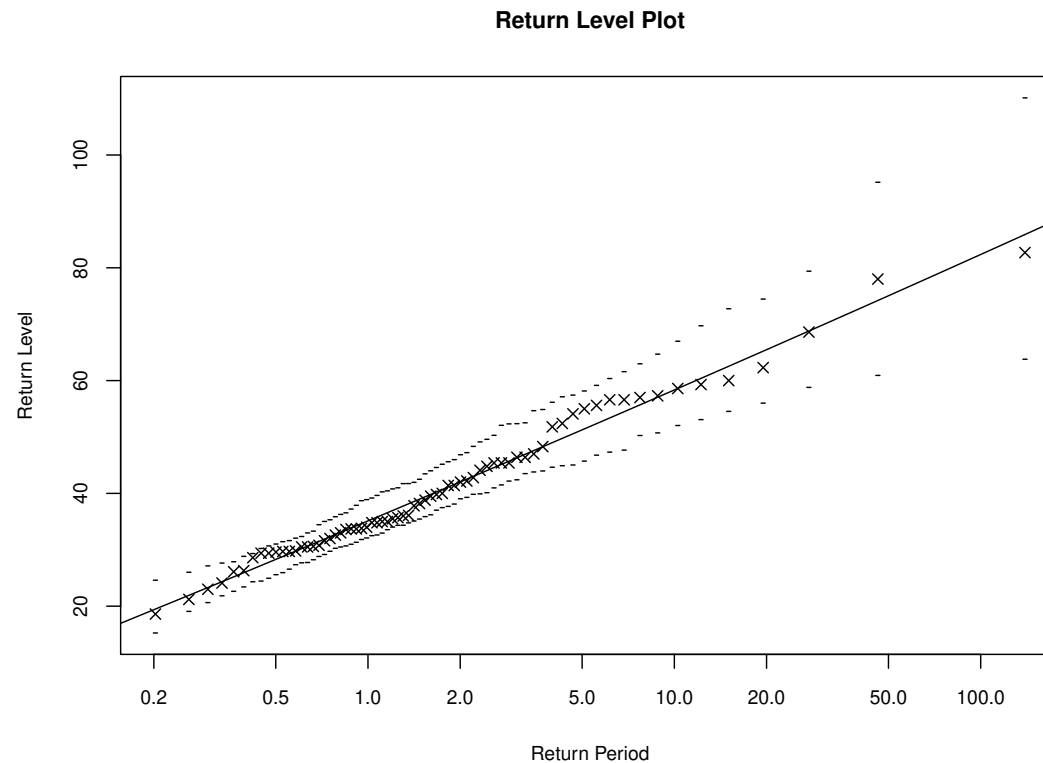
Assessing uncertainties

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences



Remark. The plot shows **empirical points**, i.e., $\{(n+1)/(n+1-i), Y_{(i)}\}$ and pointwise confidence intervals as before.

Assessing uncertainties

1. Block maxima

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- The output of `fgev` gives the standard errors for $\hat{\mu}$, $\hat{\sigma}$ and $\hat{\xi}$ from which one easily get symmetric confidence intervals, e.g.,

$$\hat{\mu} \pm z_{1-(1-\alpha)/2} \times \text{std.err}(\hat{\mu}), \quad \Phi(z_{1-(1-\alpha)/2}) = 1 - (1 - \alpha)/2.$$

- Symmetry is not always a good thing so one could use confidence intervals based on the **profile likelihood**.
- As the likelihood ratio statistics satisfies

$$W(\xi_0) := 2\{\ell(\hat{\theta}) - \ell(\hat{\theta}_{\xi=\xi_0})\} \xrightarrow{D} \chi_1^2, \quad n \rightarrow \infty,$$

we can find $I = [\xi_-, \xi_+]$ such that for all $\xi_0 \in I$

$$\Pr\{\chi_1^2 > W(\xi_0)\} > \alpha.$$

Profile likelihood: Toulouse–Blagnac

1. Block maxima

Type and Max-stability

Extremal type theorem

The three limiting families

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Domains of attraction

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Assessing uncertainties

2. Threshold exceedances

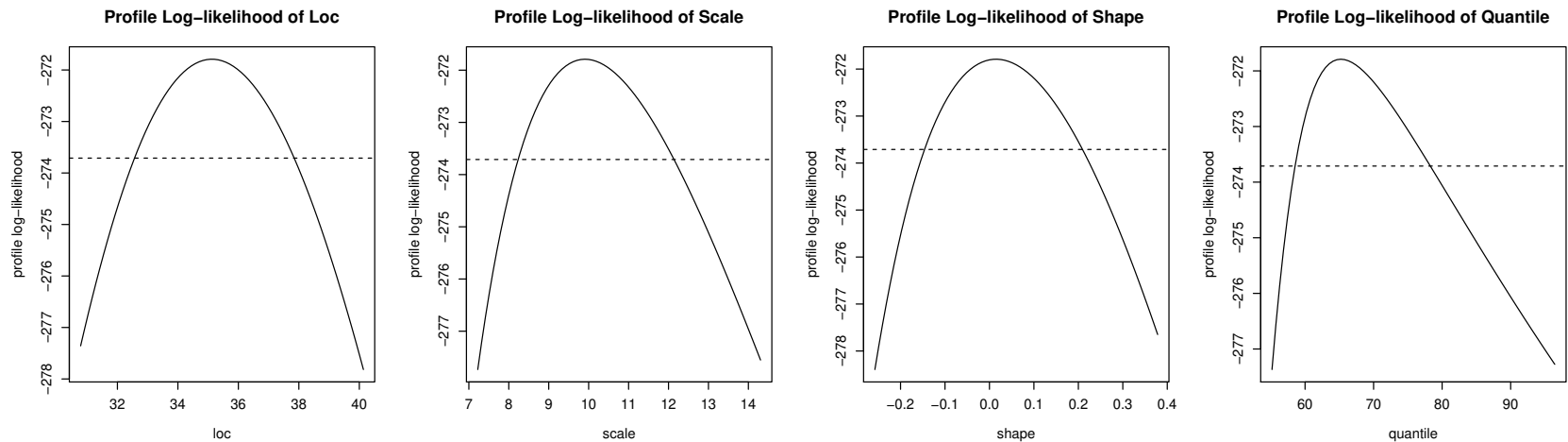
3. Point process

4. Non-stationary sequences

5. Stationary sequences

```
> plot(profile(fitted))
```

```
> plot(profile(fgev(block.max[, "precip"], prob = 0.05), "qua
```



```
fgev(block.max[, "Precip"], prob = 0.05) #@%*?!
```

- 1. Block maxima

- Type and Max-stability
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- 4. Non-stationary sequences

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- What does mean this (optional) argument $\text{prob} = p$?
- It is just a reparametrization of the GEV with parameters (y_p, σ, ξ) , i.e., we substitute μ in the density by

$$\mu = y_p + \sigma \frac{1 - \{-\log(1 - p)\}^{-\xi}}{\xi}$$

- And fit the GEV as usual.
- We can then profile the likelihood w.r.t. y_p as any other parameter!

1. Block maxima

▷ 2. Threshold
exceedances

Another representation
for extremes

GPD

Quantile

Threshold selection

3. Point process

4. Non-stationary
sequences

5. Stationary sequences

2. Threshold exceedances

Another representation for extremes

1. Block maxima

2. Threshold exceedances

▷ Another representation for extremes

GPD

Quantile

Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

- Previously we characterize extremes using block maxima

$$M_m = \max_{j=1, \dots, m} X_j.$$

- Another approach consists in considering **threshold exceedances**

$$\{X_j - u : X_j - u > 0\},$$

for some **(high enough) threshold u** .

The Generalized Pareto Distribution

1. Block maxima

2. Threshold exceedances

Another representation for extremes

▷ GPD

Quantile

Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Theorem. Let X_1, X_2, \dots be a sequence of i.i.d. random variables with distribution F and sequences $\{a_m > 0: m \geq 1\}$, $\{b_m \in \mathbb{R}: m \geq 1\}$ such that

$$\Pr\left(\frac{M_m - b_m}{a_m} \leq x\right) \longrightarrow H(x), \quad m \rightarrow \infty,$$

where H is a (non degenerate) GEV. Then

$$\Pr\{X > u_m(u+x) \mid X > u_m(u)\} \longrightarrow 1 - \tilde{H}(x), \quad m \rightarrow \infty,$$

with $u_m(x) = a_m x + b_m$ for all $x \in (0, \infty)$ and

$$\tilde{H}(x) = \begin{cases} 1 - \left(1 + \xi \frac{x}{\tau}\right)^{-1/\xi}, & \xi \neq 0 \\ 1 - \exp\left(-\frac{x}{\tau}\right), & \xi = 0, \end{cases}$$

where $\tau = \sigma + \xi(u - \mu)$. The limiting distribution is the **Generalized Pareto Distribution GPD(τ, ξ)**.

Statistical interpretation

1. Block maxima

2. Threshold exceedances

Another representation for extremes

▷ GPD

Quantile

Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

- We observe a time series of, say, daily values X_1, X_2, \dots supposed (for now) to be independent and identically distributed from F .
- We choose, **and not estimate**, a large enough threshold u —common practice is to take $u = F^{-1}(0.95)$ but see later.
- Compute the exceedances

$$\{X_i - u : X_i > u\}.$$

- And fit a GPD to these exceedances.

Environmental applications

- 1. Block maxima

- 2. Threshold exceedances

- Another representation for extremes
- ▷ GPD
- Quantile
- Threshold selection

- 3. Point process

- 4. Non-stationary sequences

- 5. Stationary sequences

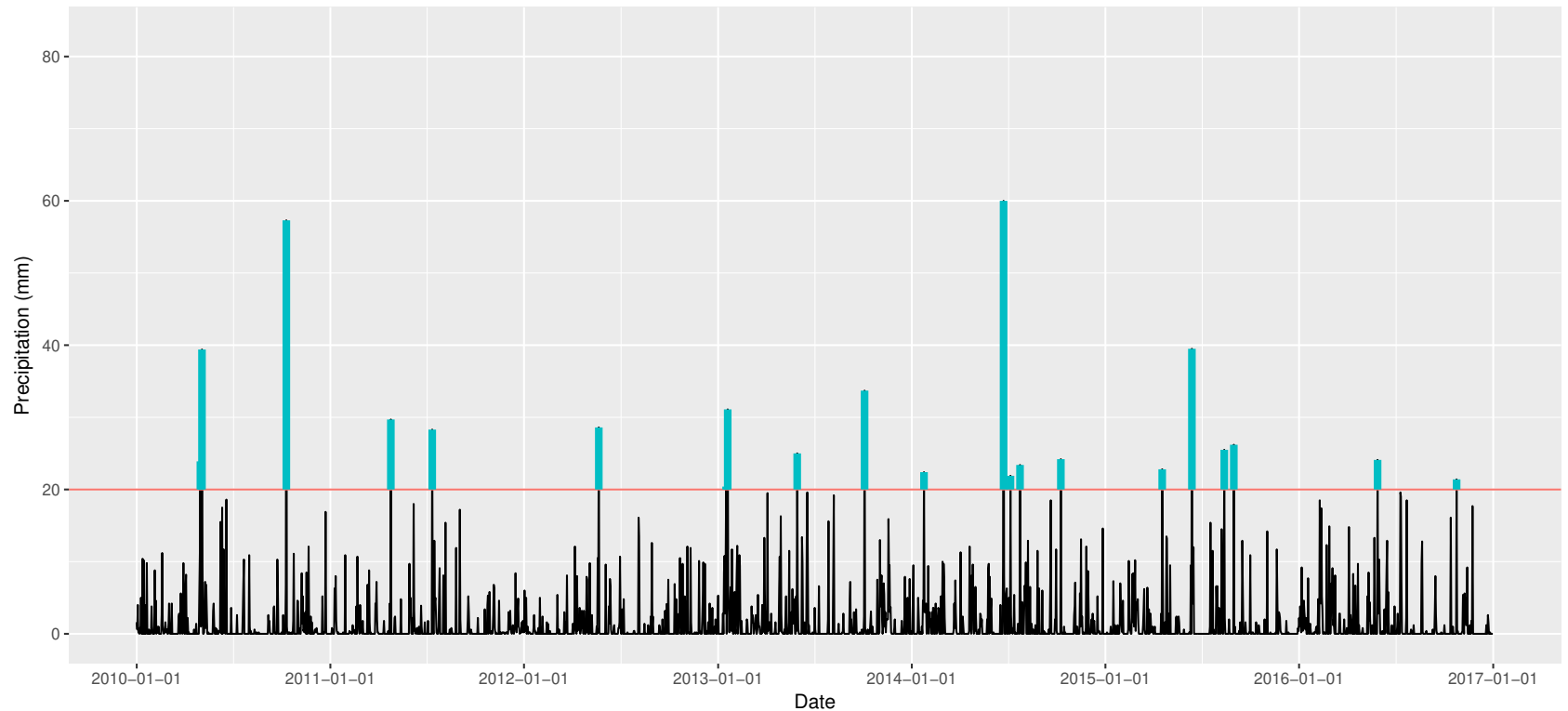


Figure 5: *Exceedances above $u = 20$ (mm) recorded at Toulouse–Blagnac.*

- Watch out for seasonality, temporal dependences

Financial applications

- 1. Block maxima
- 2. Threshold exceedances
- Another representation for extremes
- ▷ GPD
- Quantile
- Threshold selection
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences

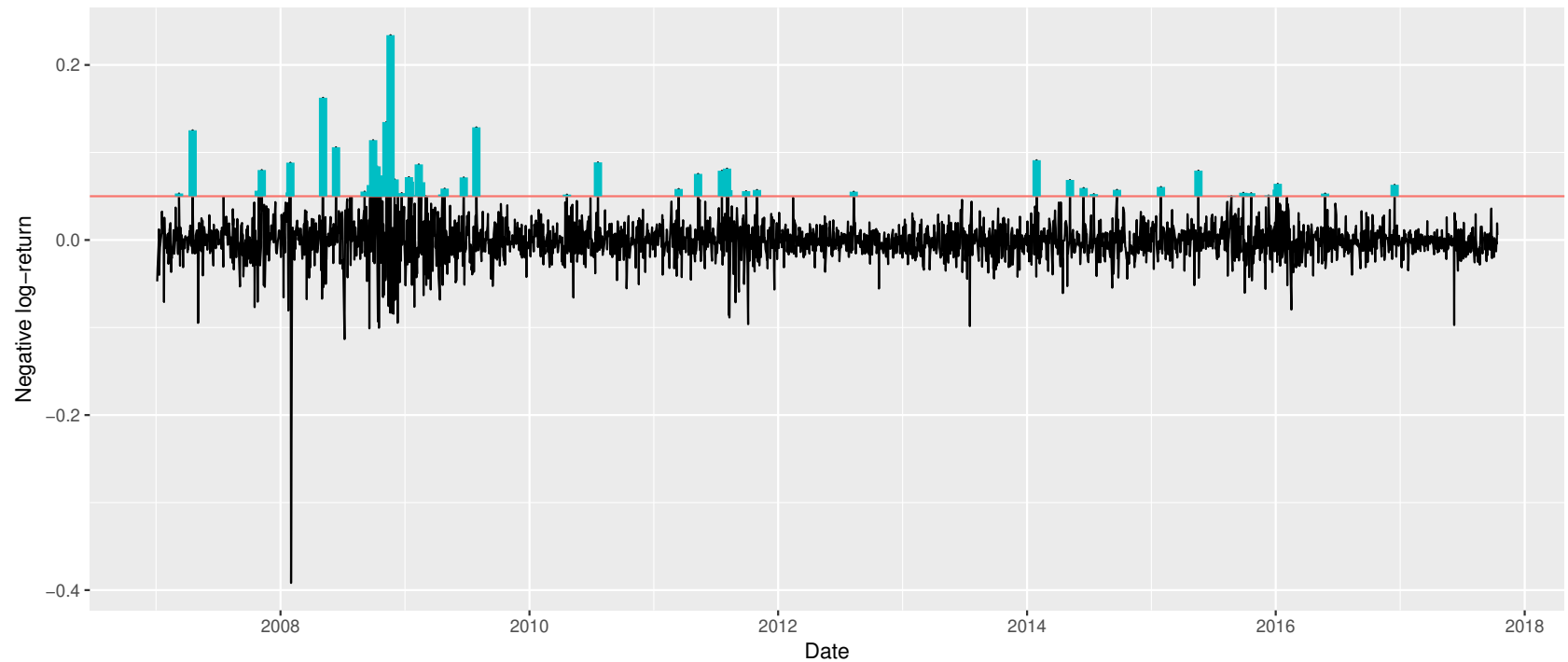


Figure 6: *(Negative) Log-returns exceedances with threshold $u = 0.1$ —Yahoo closing prices.*

Quantiles for the GPD

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

▷ Quantile

Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

- Let $p \in (0, 1)$, the quantile y_p of a $\text{GPD}(\tau, \xi)$ with exceedance probability p , i.e., $F(y_p) = 1 - p$, is

$$y_p = \tau \frac{p^{-\xi} - 1}{\xi}.$$

- Or depending on the situation we can write

$$y_p = u + \tau \frac{p^{-\xi} - 1}{\xi},$$

if we work on the **original** scale.

Return levels for the GPD

- 1. Block maxima
- 2. Threshold exceedances
- Another representation for extremes
- GPD
- ▷ Quantile
- Threshold selection
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences

- Recall that the GPD is an asymptotic model for **conditional exceedances**.
- For some threshold u , the return level $y_p > u$ of with exceedance probability p satisfies

$$\Pr(X > y_p) = \Pr(X > y_p \mid X > u) \Pr(X > u) = p.$$

- Hence we get

$$y_p = u + \tau \frac{(p/p(u))^{-\xi} - 1}{\xi}, \quad p(u) = \Pr(X > u),$$

and y_p is expected to be exceeded once every **$1/p$ observations**.

- It is often more convenient to work on an annual scale so if we have n_y observations per year, y_p is expected to be exceeded once every **$1/(pn_y)$ years**.

Example: Yahoo negative log-returns

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

▷ Quantile

Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

```
> library(evd)## For EVT
> library(quantmod)## To get the Yahoo data
> getSymbols("YH00", src = "google")
> head(YH00)## YH00 is a xts object giving the *raw* data
> nlogreturn <- -diff(log(YH00$YH00.Close))
> (fitted <- fpot(nlogreturn, 0.05, npp = 250))
```

```
Call: fpot(x = nlogreturn, threshold = 0.05, npp = 250)
Deviance: -320.2334
```

```
Threshold: 0.05
Number Above: 58
Proportion Above: 0.0214
```

```
Estimates
```

```
  scale  shape
0.01743 0.28939
```

```
Standard Errors
```

```
  scale  shape
0.003793 0.179451
```

```
...
```

QQ-plot: Yahoo

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

▷ Quantile

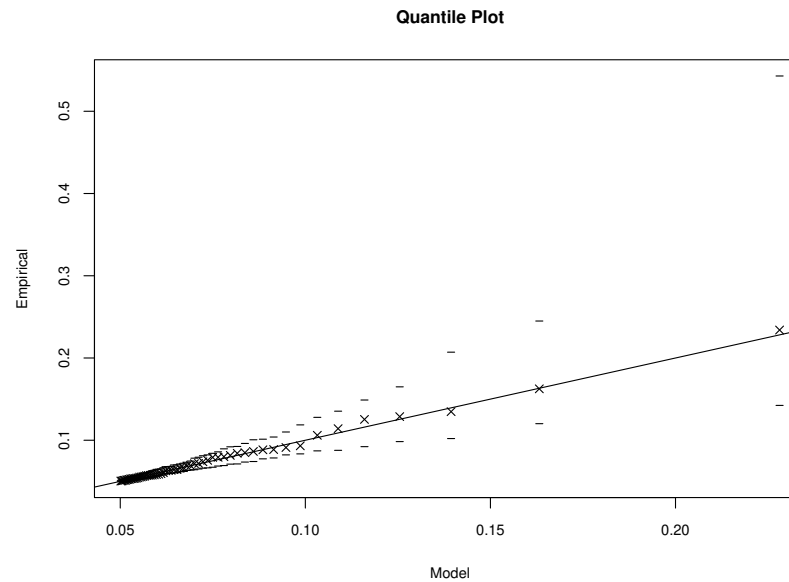
Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

```
> qq(fitted)
```



Return level plot: Yahoo

- 1. Block maxima

- 2. Threshold exceedances

- Another representation for extremes

- GPD

- ▷ Quantile

- Threshold selection

- 3. Point process

- 4. Non-stationary sequences

- 5. Stationary sequences

```
> rl(fitted)
```

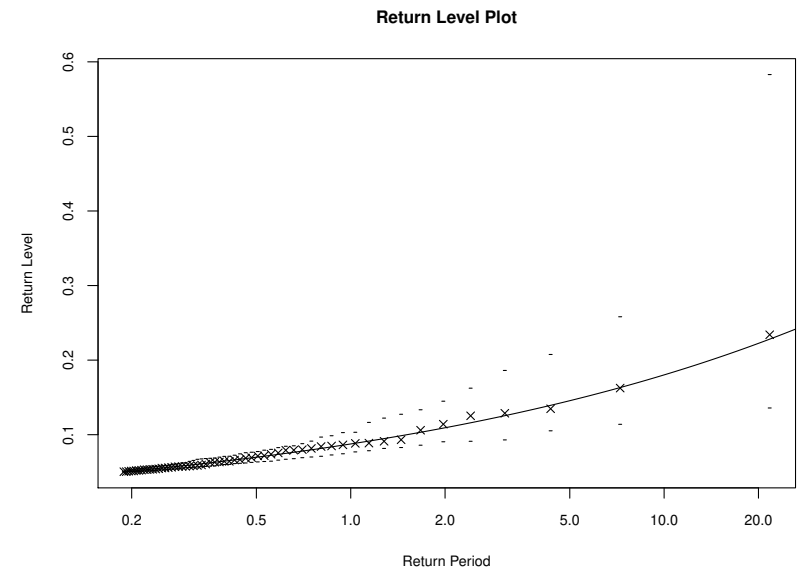
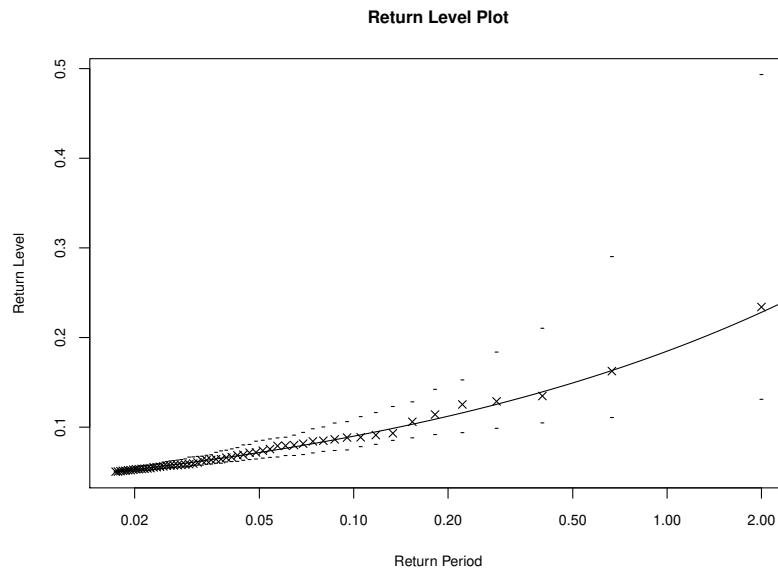
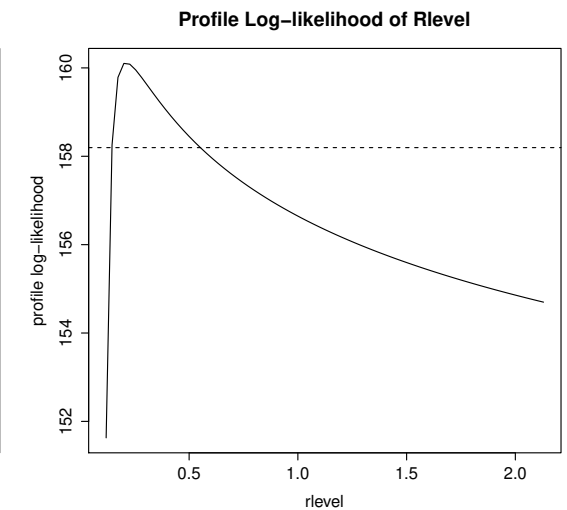
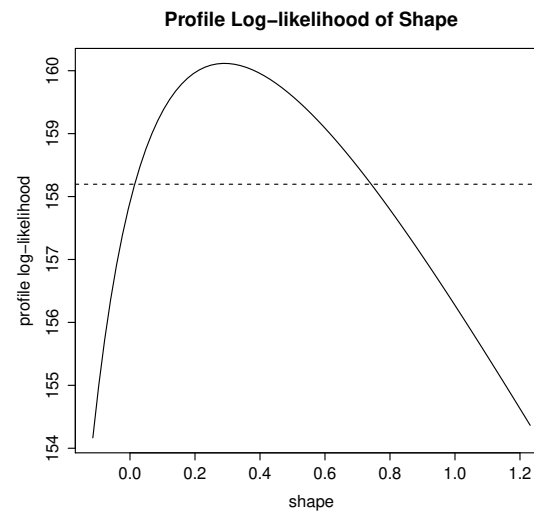
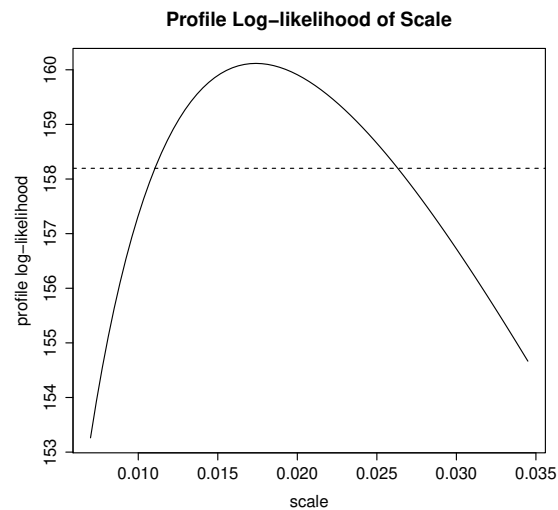


Figure 7: Return level plot for the Yahoo data set. Left: without specifying the npp argument. Right: With $npp = 250$.

Profile likelihood: Yahoo

- 1. Block maxima
- 2. Threshold exceedances
- Another representation for extremes
- GPD
- ▷ Quantile
- Threshold selection
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences

```
> plot(profile(fitted))  
> plot(profile(fpot(nlogreturn, 0.05, mper = 20, npp = 250)),  
       "rlevel")
```



Threshold selection

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

Quantile

▷ Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

- Remember that threshold u is not a parameter of the GPD. We should fix it. But how?
- Intuitively one should expect a **bias/variance tradeoff**:
 - if u is too low: far from the asymptotic regime \rightarrow bias
 - if u is too high: only few exceedances \rightarrow large variance
- The basic idea is to check whether some properties of the GPD are met for a sequence of increasing thresholds $\{u_m : m \geq 1\}$.

Threshold stability of the GPD

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

Quantile

▷ Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Proposition 1. *If $X - u_0 \mid X > u_0 \sim \text{GPD}(\tau, \xi)$ then for all $u \geq u_0$,*

$$X - u \mid X > u \sim \text{GPD}(\tilde{\tau}, \xi), \quad \tilde{\tau} = \tau + \xi(u - u_0).$$

Mean residual life plot

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

Quantile

▷ Threshold selection

3. Point process

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5. Stationary sequences

Proposition 2. *If $X - u_0 \mid X > u_0 \sim \text{GPD}(\tau, \xi)$, $\xi < 1$, then for all $u \geq u_0$*

$$MRL(u) = \mathbb{E}(X - u \mid X > u) = \frac{\tau(u_0) + \xi u}{1 - \xi}$$

- Hence if the GPD assumption is sensible for some threshold u_0 , then the function $u \mapsto MRL(u)$ should be **linear in u** , $u \geq u_0$.
- We then define a sequence of increasing threshold $\{u_m : m \geq 1\}$, compute the empirical version of $MRL(u_m)$ and check for linearity.

Mean residual life plot: Yahoo

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

Quantile

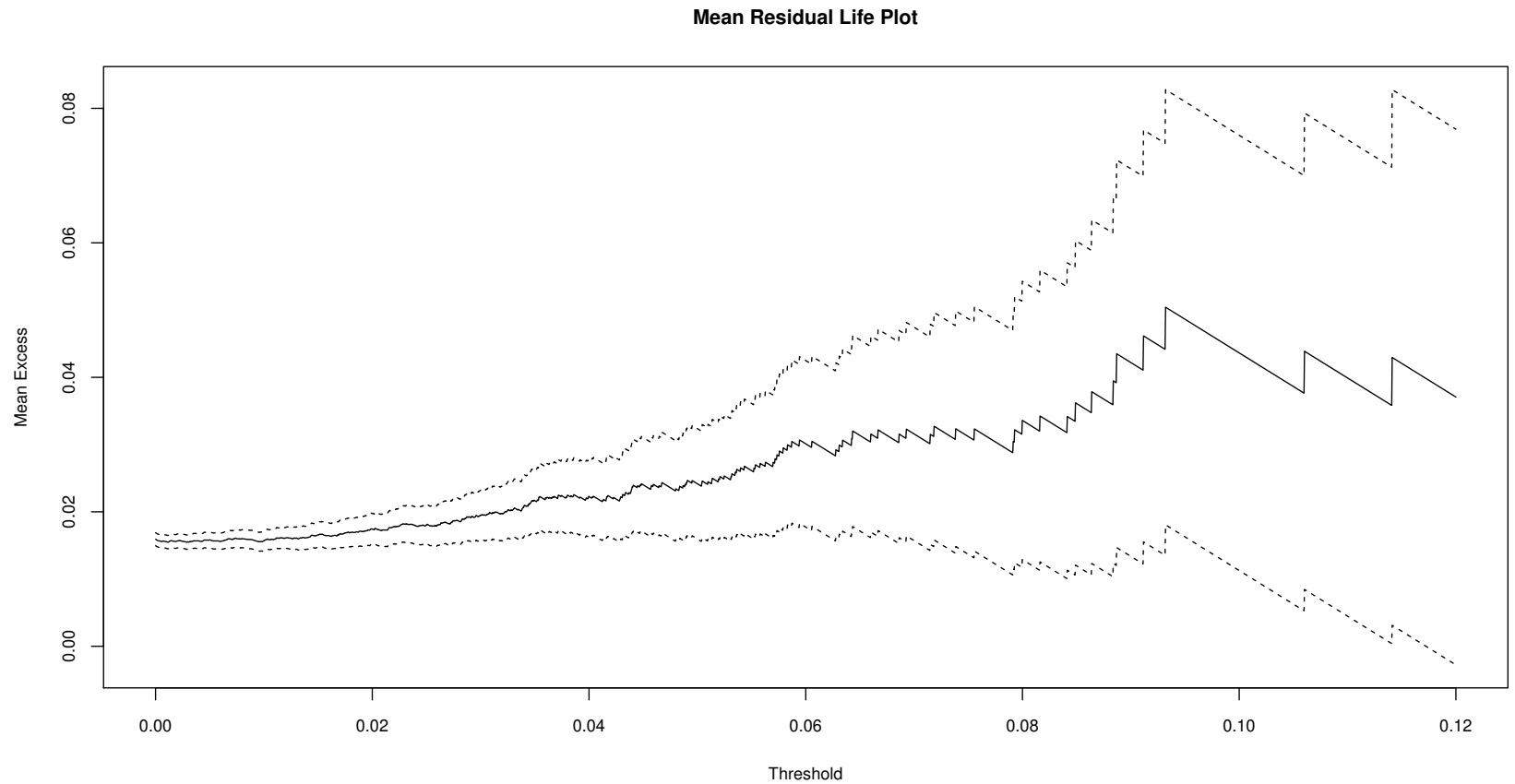
▷ Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

```
> mrlplot(nlogreturn, c(0, 0.12))
```



Parameters stability

1. Block maxima

2. Threshold exceedances

Another representation for extremes

GPD

Quantile

▷ Threshold selection

3. Point process

4. Non-stationary sequences

5. Stationary sequences

- Let $X - u_0 \mid \{X > u_0\} \sim \text{GPD}(\tau, \xi)$ then we know that for all $u \geq u_0$

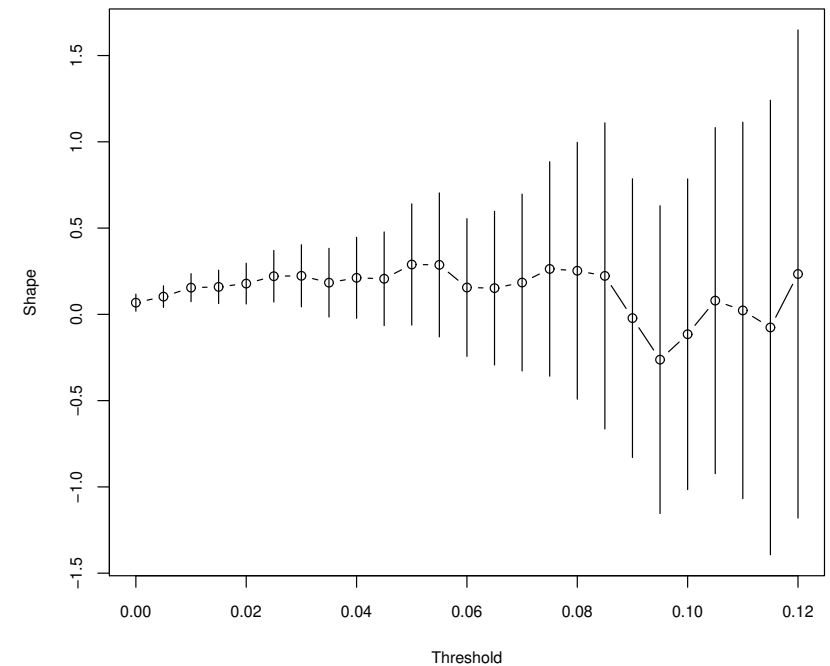
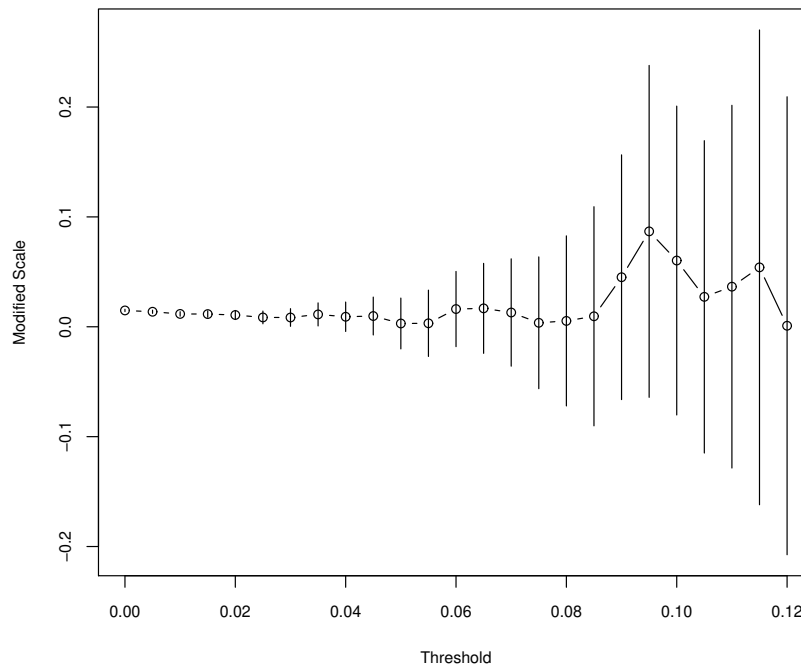
$$X - u \mid \{X > u\} \sim \text{GPD}(\tilde{\tau}, \xi), \quad \tilde{\tau} = \tau + \xi(u - u_0).$$

- Hence the function $\tau_* : u \mapsto \tilde{\tau} - \xi u$ should be constant and the shape parameter should be the same.
- It suggests to define a sequence of increasing threshold $\{u_m : m \geq 1\}$, fit a GPD to exceedances above threshold u_m , and check for stability of τ_* and ξ .

Parameters stability: Yahoo

- 1. Block maxima
- 2. Threshold exceedances
- Another representation for extremes
- GPD
- Quantile
- ▷ Threshold selection
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences

```
> tcplot(nlogreturn, c(0, 0.12))
```



□ A threshold around $u = 0.04$ seems appropriate here.

1. Block maxima

2. Threshold
exceedances

▷ 3. Point process

Point processes

Convergence to a PPP

Quantile

4. Non-stationary
sequences

5. Stationary sequences

3. Point process

Point processes

1. Block maxima

2. Threshold exceedances

3. Point process

▷ Point processes

Convergence to a PPP
Quantile

4. Non-stationary sequences

5. Stationary sequences

Definition 5 (Informal). A point process $\{X_i: i \in I\}$ is a **stochastic process** whose realization is a collection of points “falling” in a space \mathcal{X} . These points are often called atoms.

- The distribution of a point process is characterized through its **counting measure**

$$N(A) = \sum_{i \in I} \delta_{X_i}(A),$$

$A \subset \mathcal{X}$ Borel set and δ the Dirac function.

- Its **intensity measure** is defined by

$$\Lambda: A \longmapsto \mathbb{E}\{N(A)\}.$$

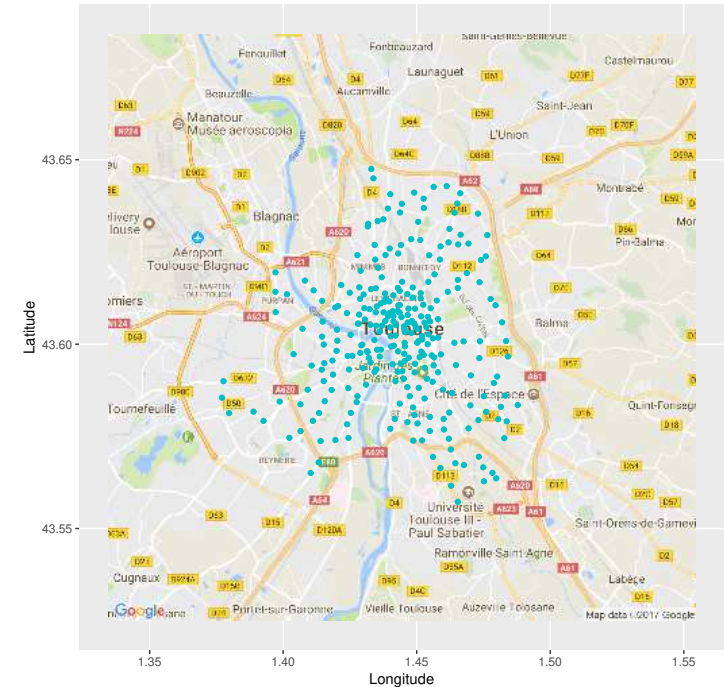


Figure 8: Locations of the bike share program in Toulouse. Can be seen as a point process on $\mathcal{X} = \text{Toulouse}$.

Poisson point process

1. Block maxima

2. Threshold exceedances

3. Point process

▷ Point processes

Convergence to a PPP
Quantile

4. Non-stationary sequences

5. Stationary sequences

Definition 6. A point process with intensity measure Λ is a **Poisson point process** if for all $k \geq 1$ and disjoint Borel sets $A, A_1, \dots, A_k \subset \mathcal{X}$,

- i) $N(A) \sim \text{Poisson}\{\Lambda(A)\}$;
- ii) $N(A_1), \dots, N(A_k)$ are independent random variables.

Remark. The intensity measure Λ is not necessarily finite. We only require it to be σ -finite, i.e., one may have $\Lambda(\mathcal{X}) = \infty$ but we can find a partition $\cup_{i \in I} A_i = \mathcal{X}$ such that $\Lambda(A_i) < \infty$, $i \in I$, where I is at most countable.

Reminder: Likelihood of a PPP

1. Block maxima

2. Threshold exceedances

3. Point process

▷ Point processes

Convergence to a PPP

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Definition 7. A Poisson point process on \mathcal{X} with intensity measure Λ is **regular** if for all Borel set $A \subset \mathcal{X}$

$$\Lambda(A) = \int_A \lambda(s) ds.$$

The function λ is non-negative and is called the **intensity function**.

Proposition 3. Let $\{X_1, \dots, X_n\}$ be a realization of a Poisson point process on \mathcal{X} with intensity measure Λ . The likelihood is

$$\exp \{-\Lambda(\mathcal{X})\} \prod_{i=1}^n \lambda(X_i).$$

Convergence to a PPP

1. Block maxima

2. Threshold exceedances

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Point processes

▷ Convergence to a PPP

Quantile

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Theorem. Under the framework of convergence of M_m to the GEV, the sequence of point processes living in $\mathcal{X} = [0, 1] \times \mathbb{R}$

$$\{\mathcal{P}_m\}_{m \geq 1} = \left\{ \left(\frac{i}{m+1}, \frac{X_i - b_m}{a_m} \right) : i = 1, \dots, m \right\}_{m \geq 1}$$

converges to a **Poisson point process** (PPP) on $[0, 1] \times C$ with intensity measure

$$\Lambda\{[a, b] \times (z, \infty)\} = (b - a) \left(1 + \xi \frac{z - \mu}{\sigma} \right)^{-1/\xi},$$

where $C = \{x \in \mathbb{R} : 1 + \xi(x - \mu)/\sigma > 0\}$.

Illustration convergence to a PPP

- 1. Block maxima
- 2. Threshold exceedances
- 3. Point process
 - Point processes
 - Convergence to a
 - ▷ PPP
 - Quantile
- 4. Non-stationary sequences
- 5. Stationary sequences

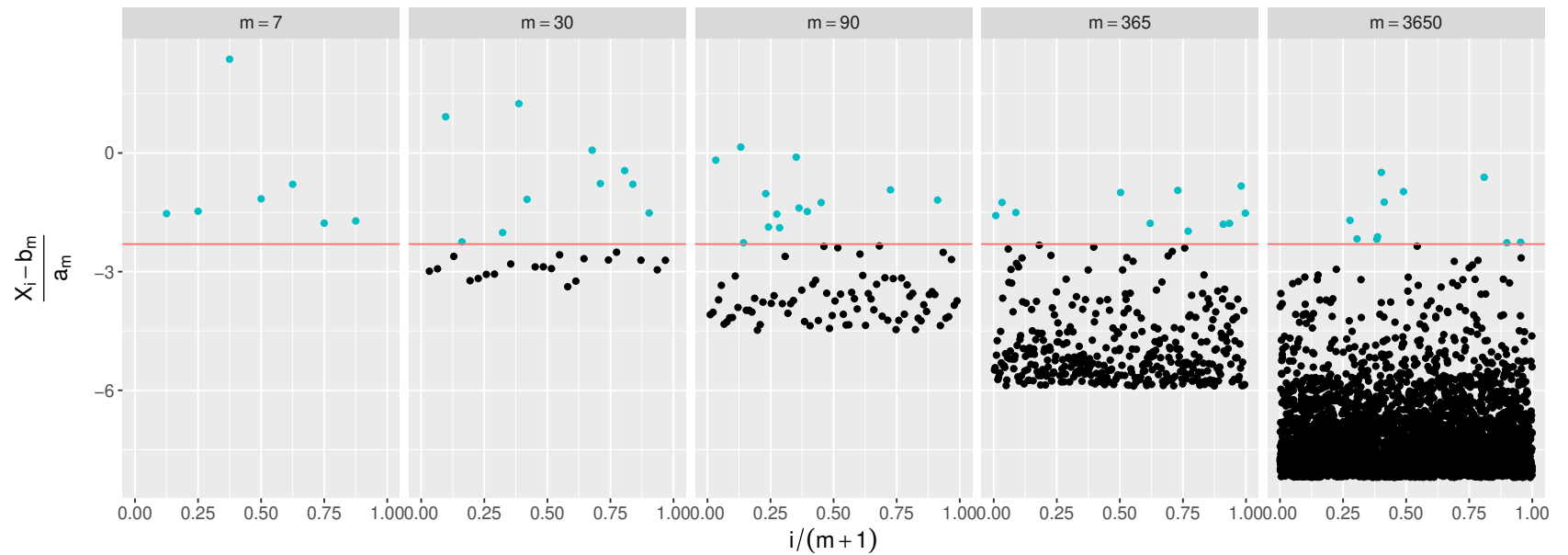


Figure 9: Illustration of the convergence to a PPP with $m = 7, 30, 90, 365, 3650$ for standard Exponential random variables— $a_m = 1$ and $B_m = \log m$. The threshold is $u = -\log 10$.

Statistical interpretation

- For a threshold u large enough, we fit a PPP to the exceedances with intensity measure

$$\Lambda\{(a, b) \times (x, \infty)\} = (b - a) \times \left(1 + \xi \frac{x - \mu}{\sigma}\right)^{-1/\xi}, \quad x > u, \quad (a, b) \subset [0, 1].$$

- In practice it is more convenient to scale the parameter to an **annual scale**, i.e.,

$$\Lambda\{(a, b) \times (x, \infty)\} = n_{\text{year}}(b - a) \times \left(1 + \xi \frac{x - \mu}{\sigma}\right)^{-1/\xi}, \quad x > u, \quad (a, b) \subset [0, 1],$$

where n_{year} is the number of years of data.

Return levels for PPP

1. Block maxima

2. Threshold exceedances

3. Point process

Point processes

Convergence to a PPP

▷ Quantile

4. Non-stationary sequences

5. Stationary sequences

- For all $x > u$, the expected number of exceedances above x in a year is

$$\mathbb{E} \left[N \left\{ (0, n_{\text{year}}^{-1}) \times (x, \infty) \right\} \right] = \Lambda \left\{ (0, n_{\text{year}}^{-1}) \times (x, \infty) \right\} = \left(1 + \xi \frac{x - \mu}{\sigma} \right)^{-1/\xi}.$$

- Hence the T -year return level y_p , $p = 1/T$, satisfies

$$T \left(1 + \xi \frac{y_p - \mu}{\sigma} \right)^{-1/\xi} = 1 \iff y_p = \mu + \sigma \frac{p^{-\xi} - 1}{\xi}.$$

Remark. It is a the return level derived from a $\text{GPD}(\sigma, \xi)$ with threshold μ restricted to the set $\{x > u\}$.

Example: Yahoo negative log-returns

1. Block maxima

2. Threshold
exceedances

3. Point process

Point processes

Convergence to a PPP

▷ Quantile

4. Non-stationary
sequences

5. Stationary sequences

```
> (fitted <- fpot(nlogreturn, 0.05, model = "pp", npp = 250))
```

```
Call: fpot(x = nlogreturn, threshold = 0.05, model = "pp", npp = 250)
```

```
Deviance: -398.3905
```

```
Threshold: 0.05
```

```
Number Above: 58
```

```
Proportion Above: 0.0213
```

```
Estimates
```

```
      loc      scale      shape  
0.08803 0.02907 0.30824
```

```
Standard Errors
```

```
      loc      scale      shape  
0.007316 0.006808 0.190213
```

```
Optimization Information
```

```
Convergence: successful
```

```
Function Evaluations: 89
```

```
Gradient Evaluations: 13
```

QQ-plot: Yahoo

1. Block maxima

2. Threshold exceedances

3. Point process

Point processes

Convergence to a PPP

▷ Quantile

4. Non-stationary sequences

5. Stationary sequences

```
> qq(fitted)
```

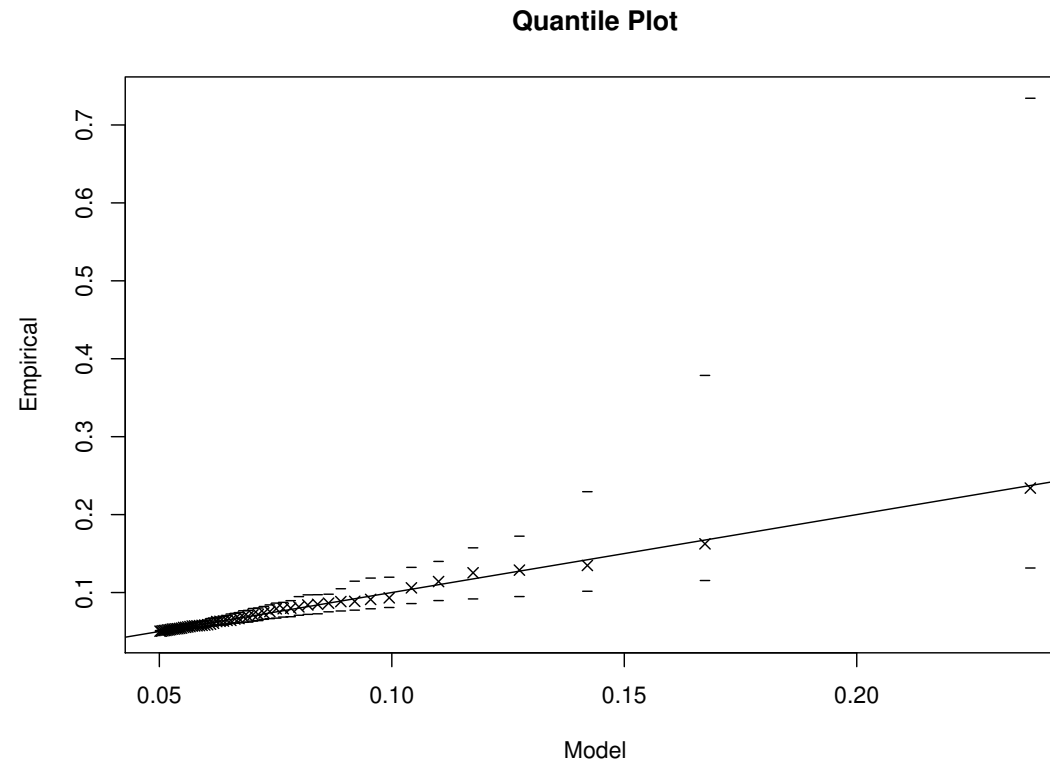


Figure 10: QQ-plots for the Yahoo data with the PPP approach.

Return level plot: Yahoo

1. Block maxima

2. Threshold exceedances

3. Point process

Point processes

Convergence to a PPP

▷ Quantile

4. Non-stationary sequences

5. Stationary sequences

```
> rl(fitted)
```

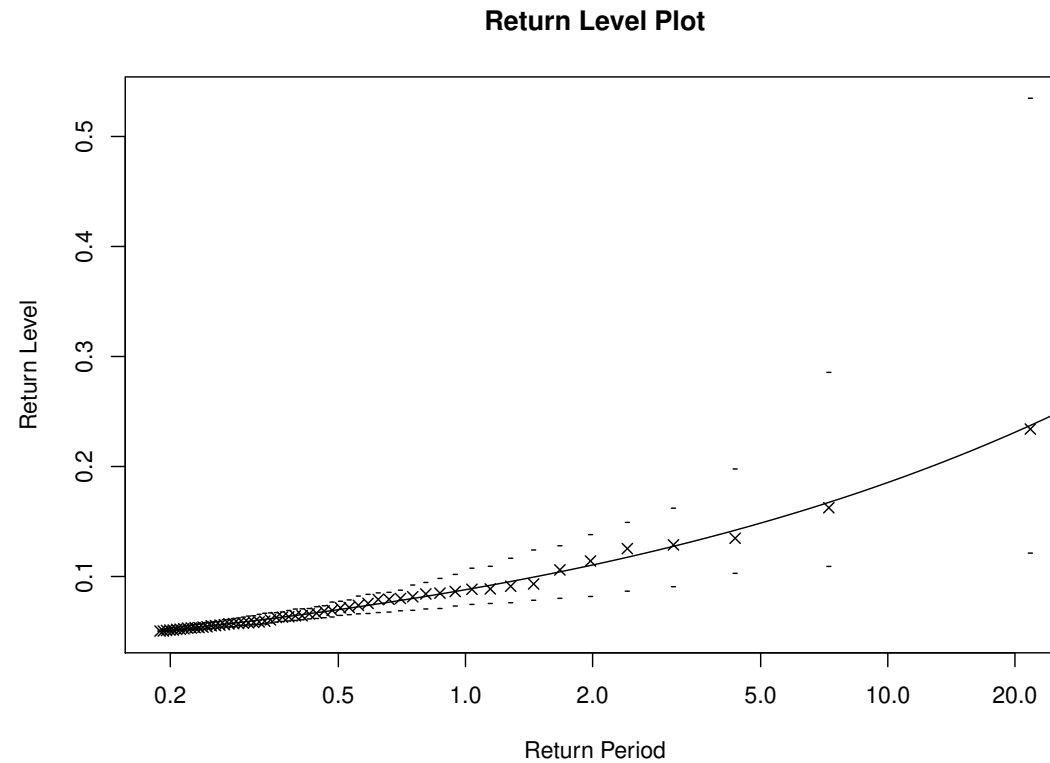


Figure 11: Return level plot for the Yahoo data set with the PPP approach.

Profile likelihood: PPP

1. Block maxima

2. Threshold exceedances

3. Point process

Point processes

Convergence to a PPP

▷ Quantile

4. Non-stationary sequences

5. Stationary sequences

- Unfortunately the evd package appears to be broken when we try to profile the PPP likelihood.
- Hence we will try to do it as a homework or during the lab session.

Yahoo: GEV / GPD / PPP approaches

```
> getSymbols("YH00", src = "google")
> head(YH00)## YH00 is a xts object giving the *raw* data
> nlogreturn <- -diff(log(YH00$YH00.Close))
> nlogreturn[1] <- 0

> quarter.max <- aggregate(YH00.Close ~ quarters(index(YH00)):years(index(YH00)),
>                           FUN = max, data = nlogreturn)

> prob <- 1 / 10##10 years return level
> gev <- fgev(quarter.max$YH00.Close)
> gpd <- fpot(nlogreturn, 0.05, npp = 250, mper = 1 / prob)
> ppp <- fpot(nlogreturn, 0.05, model = "pp", npp = 250)

> qgev(1 - prob/4, gev$param["loc"], gev$param["scale"], gev$param["shape"])
0.1691627
> gpd$param["rlevel"]
0.180289
> qgpd(1 - prob, ppp$param["loc"], ppp$param["scale"], ppp$param["shape"])
0.1854948
```

1. Block maxima

2. Threshold
exceedances

3. Point process

▷ 4. Non-stationary
sequences

Failure of the i.d.
assumption

Two strategies

Toulouse temperatures

Model with a trend

Model selection

5. Stationary sequences

4. Non-stationary sequences

Failure of the i.d. assumption

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

▷ Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

Model selection

5. Stationary sequences

- In many situations the **i.i.d.** assumption is not appropriate.
- In this section we will focus on situations in case of **failure of the i.d. assumption**;
- It is often the case with environmental processes which typically involve:
 1. **seasonality**, i.e., spring, summer, fall, winter;
 2. **trends**, e.g., global warming.

Two strategies

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

▷ Two strategies

Toulouse temperatures

Model with a trend

Model selection

5. Stationary sequences

- Two (simple) strategies are possible:
 1. you restrict your analysis to **specific** seasons, i.e., modelling **seasonal extremes**;
 2. you embed the **seasonal pattern** into the **parameters of the GEV/GPD/PPP**.
- The first approach is straightforward as it is just a classical EVT analysis applied to a subset of our data.
- The second is (very) slightly more elaborate.

An example: Toulouse summer maxima temperatures

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

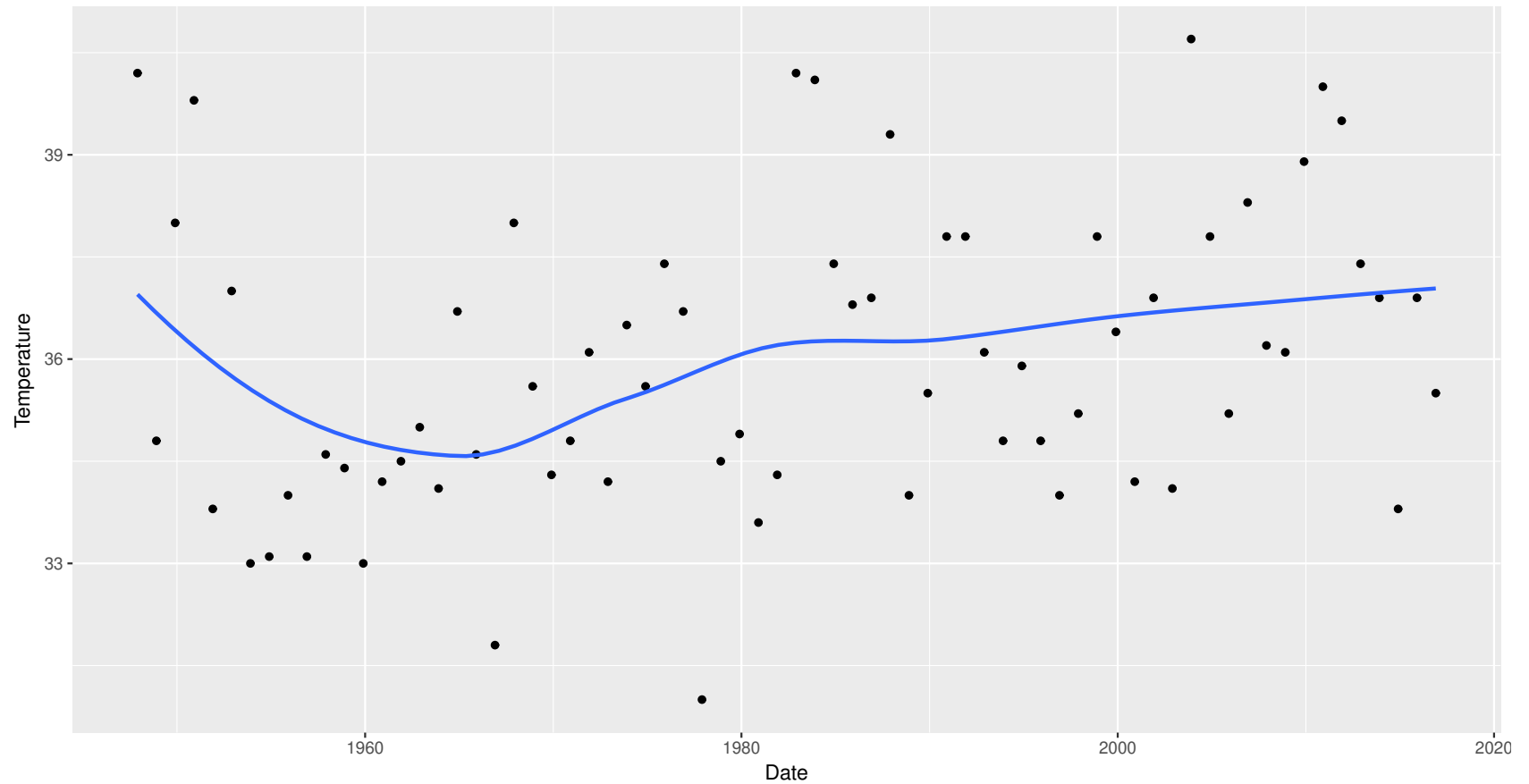
Two strategies

▷ Toulouse temperatures

Model with a trend

Model selection

5. Stationary sequences



Model with a trend

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

▷ Model with a trend

Model selection

5. Stationary sequences

Assume assume for the GEV that $\mu(t) = \beta_0 + \beta_1 t/100$ —increase of β_1 °C in a century.

```
> covar <- data.frame(year = scale(1:nrow(summer.max), scale = FALSE)) /  
100  
> (fit <- fgev(summer.max$Temperature, nsloc = covar))
```

```
Call: fgev(x = summer.max$Temperature, nsloc = covar)  
Deviance: 295.6636
```

Estimates

loc	locyear	scale	shape
35.1082	3.3582	1.8451	-0.1394

Standard Errors

loc	locyear	scale	shape
0.24441	1.16260	0.16944	0.07912

Optimization Information

Convergence: successful

Function Evaluations: 20

Gradient Evaluations: 10

Model selection

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

▷ Model selection

5. Stationary sequences

- Is this trend really necessary, i.e.,

$$H_0: \beta_1 = 0 \quad H_1: \beta_1 \neq 0?$$

- How would you do this?

Do you understand those lines?

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

▷ Model selection

5. Stationary sequences

```
> z <- abs(fit$par["locyear"] / fit$std.err["locyear"])
> 2 * pnorm(z, lower.tail=FALSE)
locyear
0.003870264
```

👉 Conclusion?

Do you understand those lines?

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

▷ Model selection

5. Stationary sequences

```
> z <- abs(fit$par["locyear"] / fit$std.err["locyear"])
> 2 * pnorm(z, lower.tail=FALSE)
locyear
0.003870264
```

👉 Conclusion?

```
> fit0 <- fgev(summer.max$Temperature)
> W <- 2 * (logLik(fit) - logLik(fit0))
> pchisq(W, df = 1, lower.tail=FALSE)
'log Lik.' 0.005746295 (df=4)
```

👉 Conclusion?

Theoretical versions

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

▷ Model selection

5. Stationary sequences

- From the asymptotic normality of the MLE we know that

$$\sqrt{n}(\hat{\beta}_1 - \beta_{1,*}) \xrightarrow{d} N(0, \sigma^2), \quad n \rightarrow \infty.$$

- Hence under H_0 , i.e., $\beta_{1,*} = 0$, we have

$$\sqrt{n} \frac{\hat{\beta}_1}{\sigma} \xrightarrow{d} N(0, 1), \quad n \rightarrow \infty.$$

This is known as the **Wald test**.

Theoretical versions (2)

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

Failure of the i.d. assumption

Two strategies

Toulouse temperatures

Model with a trend

▷ Model selection

5. Stationary sequences

- Using Taylor expansion of the log-likelihood $\ell(\theta_*)$ around $\hat{\theta}$ we have

$$\begin{aligned}\ell(\theta_*) &\dot{\sim} \ell(\hat{\theta}) + (\theta_* - \hat{\theta})^\top \nabla \ell(\hat{\theta}) + \frac{1}{2} (\theta_* - \hat{\theta})^\top \nabla^2 \ell(\hat{\theta}) (\theta_* - \hat{\theta}) \\ &\dot{\sim} \ell(\hat{\theta}) + \frac{1}{2} (\theta_* - \hat{\theta})^\top \nabla^2 \ell(\hat{\theta}) (\theta_* - \hat{\theta})\end{aligned}$$

- Hence we conclude that as $n \rightarrow \infty$

$$\begin{aligned}W = 2\{\ell(\hat{\theta}) - \ell(\theta_*)\} &= -\sqrt{n}(\theta_* - \hat{\theta})^\top \frac{1}{n} \nabla^2 \ell(\hat{\theta}) \sqrt{n}(\theta_* - \hat{\theta}) \\ &\xrightarrow{d} \chi_p^2, \quad p = |\theta_*|.\end{aligned}$$

- This is known as the **likelihood ratio test**.

1. Block maxima

2. Threshold
exceedances

3. Point process

4. Non-stationary
sequences

▷ 5. Stationary
sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

5. Stationary sequences

Stationary sequences

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

▷ Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

- So far we analyzed the asymptotic behaviour of **i.i.d.** random variable.
- In many situations, e.g., Yahoo time series, this assumption is **unrealistic** !
- What happens there is some **serial dependence** ?

$D(u_n)$ condition

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

▷ $D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

Definition 8. A **stationary sequence** $\{X_i : i \geq 1\}$ is said to satisfy the $D(u_n)$ condition, if for all $i_1 < \dots < i_p < j_1 < \dots < j_q$ with $j_1 - i_p > \ell_n$, we have

$$|\Pr(X_{i_1} \leq u_n, \dots, X_{i_p} \leq u_n, X_{j_1} \leq u_n, \dots, X_{j_q} \leq u_n) - \Pr(X_{i_1} \leq u_n, \dots, X_{i_p} \leq u_n) \Pr(X_{j_1} \leq u_n, \dots, X_{j_q} \leq u_n)| \leq \alpha(n, \ell),$$

where $\alpha(n, \ell_n) \rightarrow 0$ for some sequences $\ell_n = o(n)$ as $n \rightarrow \infty$.

- Roughly speaking the $D(u_n)$ condition imposes that the two blocks X_i 's and X_j 's are close to being independent as long as they are sufficiently “far apart”.
- One way to avoid **long-range dependence**.

1. Block maxima

2. Threshold
exceedances

3. Point process

4. Non-stationary
sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

▷ GEV revisited

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Cluster maxima

Decustering

Theorem. Let X_1, X_2, \dots be a *stationary sequence* and define $M_n = \max(X_1, \dots, X_n)$. If there exists 2 sequences $\{a_n > 0\}$ and $\{b_n \in \mathbb{R}\}$ such that

$$\Pr\left(\frac{M_n - b_n}{a_n} \leq z\right) \longrightarrow G(z), \quad n \rightarrow \infty,$$

where G is a non degenerate distribution and *the $D(u_n)$ condition is met* with $u_n = a_n z + b_n$ for all $z \in \mathbb{R}$ such that $G(z) > 0$, then *necessarily G is of the GEV form.*

1. Block maxima

2. Threshold
exceedances

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Cluster maxima

Declustering

Theorem. Let X_1, X_2, \dots be a *stationary sequence* and define $M_n = \max(X_1, \dots, X_n)$. If there exists 2 sequences $\{a_n > 0\}$ and $\{b_n \in \mathbb{R}\}$ such that

$$\Pr\left(\frac{M_n - b_n}{a_n} \leq z\right) \longrightarrow G(z), \quad n \rightarrow \infty,$$

where G is a non degenerate distribution and *the $D(u_n)$ condition is met* with $u_n = a_n z + b_n$ for all $z \in \mathbb{R}$ such that $G(z) > 0$, then *necessarily G is of the GEV form.*

Remark. The GEV parameters for the stationary sequence **will not be the same** as the ones for an i.i.d. sequence.

Stationary sequence \leftrightarrow i.i.d. sequence

1. Block maxima

2. Threshold exceedances

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Stationary sequences

$D(u_n)$ condition

▷ GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

Theorem. Let X_1, X_2, \dots be a *stationary sequence* and X_1^*, X_2^*, \dots an *i.i.d. sequence* with the same marginal distribution as the X_i 's. Define $M_n = \max(X_1, \dots, X_n)$ and $M_n^* = \max(X_1^*, \dots, X_n^*)$. Under the hypothesis of the previous theorem, we have

$$\Pr\left(\frac{M_n^* - b_n}{a_n} \leq z\right) \longrightarrow G_*(z), \quad n \rightarrow \infty,$$

if and only if

$$\Pr\left(\frac{M_n - b_n}{a_n} \leq z\right) \longrightarrow G(z), \quad n \rightarrow \infty,$$

where

$$G(z) = G_*^\theta(z), \quad 0 < \theta \leq 1.$$

👉 θ is called the *extremal index*.

Impact of the extremal index

- 1. Block maxima
 - 2. Threshold exceedances
 - 3. Point process
 - 4. Non-stationary sequences
 - 5. Stationary sequences
- Stationary sequences
 $D(u_n)$ condition
▷ GEV revisited
Extremal index
Exceedances
Cluster maxima
Declustering

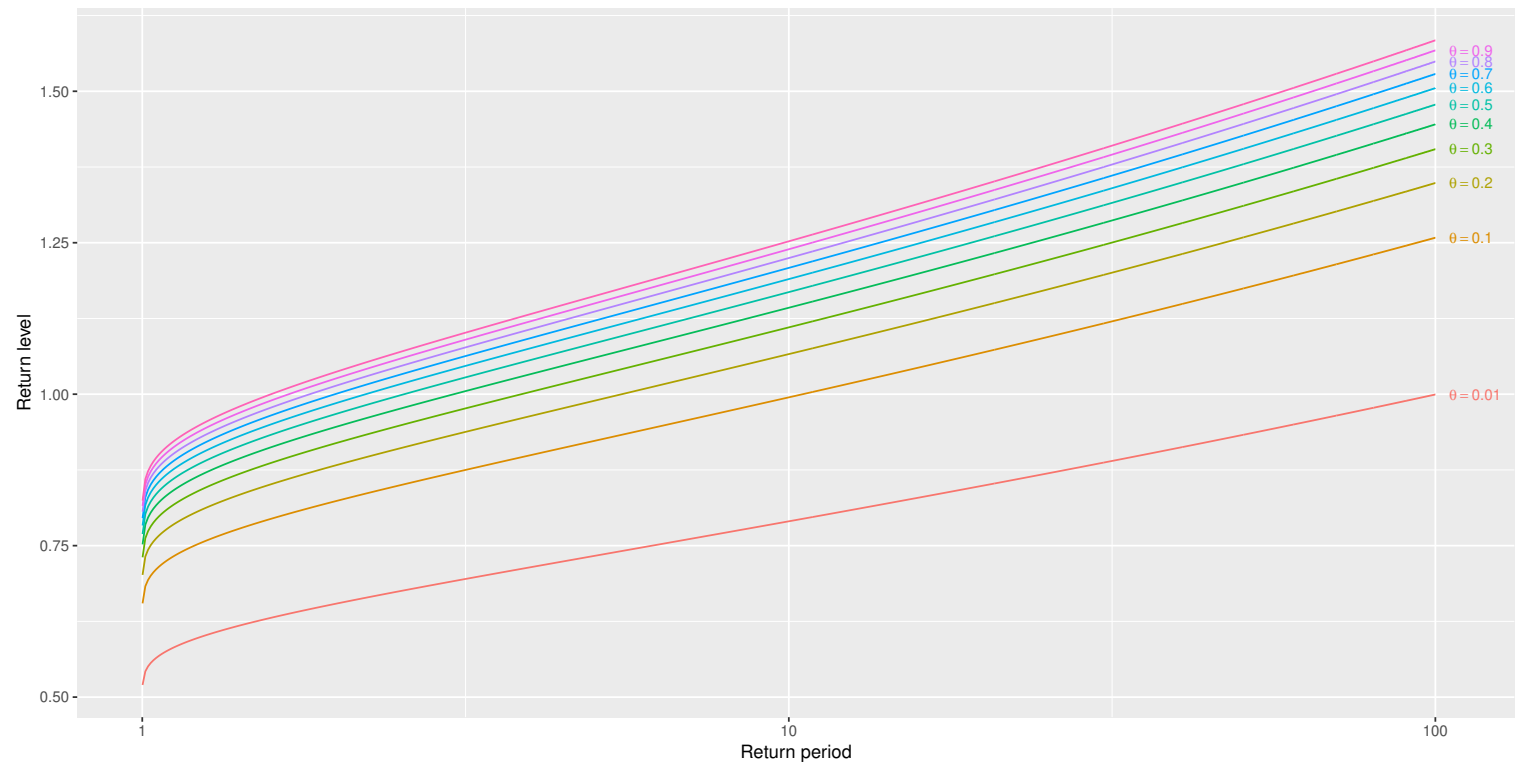


Figure 12: *Impact of the extremal index θ on return levels.*

Impact of the extremal index

- 1. Block maxima
- 2. Threshold exceedances
- 3. Point process
- 4. Non-stationary sequences
- 5. Stationary sequences
- Stationary sequences
- $D(u_n)$ condition
- ▷ GEV revisited
- Extremal index
- Exceedances
- Cluster maxima
- Declustering

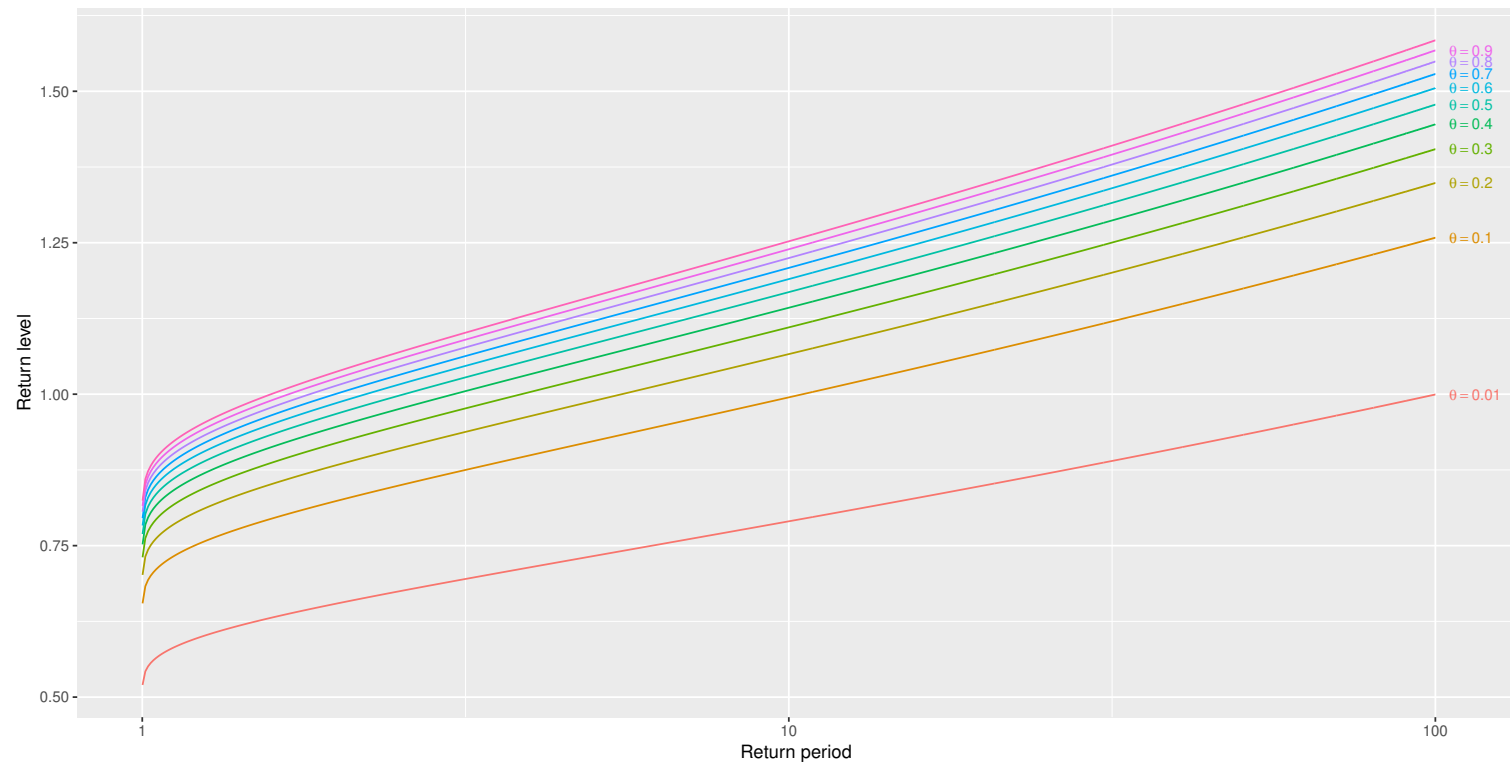


Figure 12: *Impact of the extremal index θ on return levels.*

- As expected, M_n is stochastically smaller than M_n^* —as maxima taken over dependent r.v. is likely to be smaller than for independent r.v.

Connection between G and G_*^θ

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

▷ GEV revisited

Extremal index

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Declustering

□ Note that we have

$$\begin{aligned} G_*^\theta(z) &= \exp \left\{ -\theta \left(1 + \xi \frac{z - \mu}{\sigma} \right)^{-1/\xi} \right\} \\ &= \exp \left\{ - \left(1 + \xi \frac{z - \mu_*}{\sigma_*} \right)^{-1/\xi} \right\}, \end{aligned}$$

where $\mu_* = \mu - \frac{\sigma}{\xi} (1 - \theta^\xi)$, $\sigma_* = \sigma \theta^\xi$.

Statistical interpretation

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

▷ GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

👉 No change for block maxima of stationary sequence, since you will estimate μ_* , σ_* and ξ directly.

□ Wait!!! There is dependence so the likelihood **is not**

$$L(\mu, \sigma, \xi; m_1, \dots, m_{\tilde{n}}) = \prod_{i=1}^{\tilde{n}} f_{GEV}(m_i; \mu, \sigma; \xi) \dots$$

Statistical interpretation

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

▷ GEV revisited

Extremal index

Exceedances

Cluster maxima

Declustering

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□ Wait!!! There is dependence so the likelihood **is not**

$$L(\mu, \sigma, \xi; m_1, \dots, m_{\tilde{n}}) = \prod_{i=1}^{\tilde{n}} f_{GEV}(m_i; \mu, \sigma; \xi) \dots$$

□ Yes but no! If **beginnings / endings of blocks are well defined**¹, assumption of mutual independence between block maxima makes sense \Rightarrow **Likelihood still valid.**

👉 This will be however a bit different for the GPD // PPP approaches.

¹Why should it always be “calendar year” blocks?

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

▷ Extremal index

Exceedances

Cluster maxima

Decustering

□ The extremal index θ has two alternative definitions:

– As the **reciprocal of the limiting expected cluster size**

$$\theta^{-1} = \lim_{n \rightarrow \infty} \mathbb{E} \left(\sum_{i=1}^{p_n} 1_{\{X_i > u_n\}} \mid M_{p_n} > u_n \right),$$

for sequences such that $n\{1 - F(u_n)\} \rightarrow \lambda \in (0, \infty)$ and $p_n = o(n)$.

– As the **limiting probability that an exceedance over u_n is the last one**

$$\theta = \lim_{n \rightarrow \infty} \Pr \{ \max(X_2, \dots, X_{p_n}) \leq u_n \mid X_1 \geq u_n \}.$$

Watch out!

1. Block maxima

2. Threshold exceedances

3. Point process

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5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

▷ Extremal index

Exceedances

Cluster maxima

Declustering

- Consider the 10–years return event $A = \{X > z_{10}\}$.
- This event **is expected** to occur 10 times in a century.

Watch out!

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

▷ Extremal index

Exceedances

Cluster maxima

Declustering

- Consider the 10–years return event $A = \{X > z_{10}\}$.
- This event **is expected** to occur 10 times in a century.
- However we have

$$\Pr(A \text{ not seen in the next 10 years}) = \begin{cases} \left(1 - \frac{1}{10}\right)^{10} \approx 0.35, & \theta = 1 \\ \left(1 - \frac{1}{10}\right)^{10\theta} = 0.90, & \theta = 0.1. \end{cases}$$

Watch out!

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

▷ Extremal index

Exceedances

Cluster maxima

Decustering

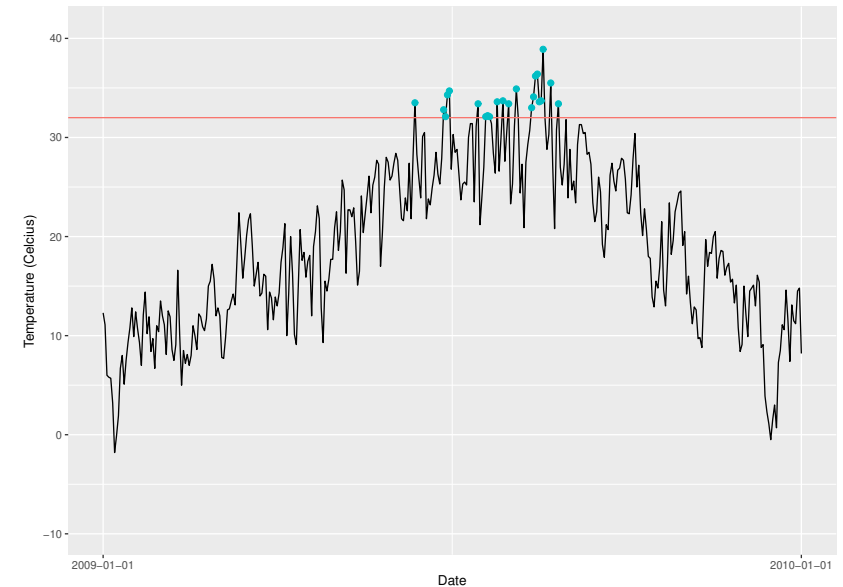
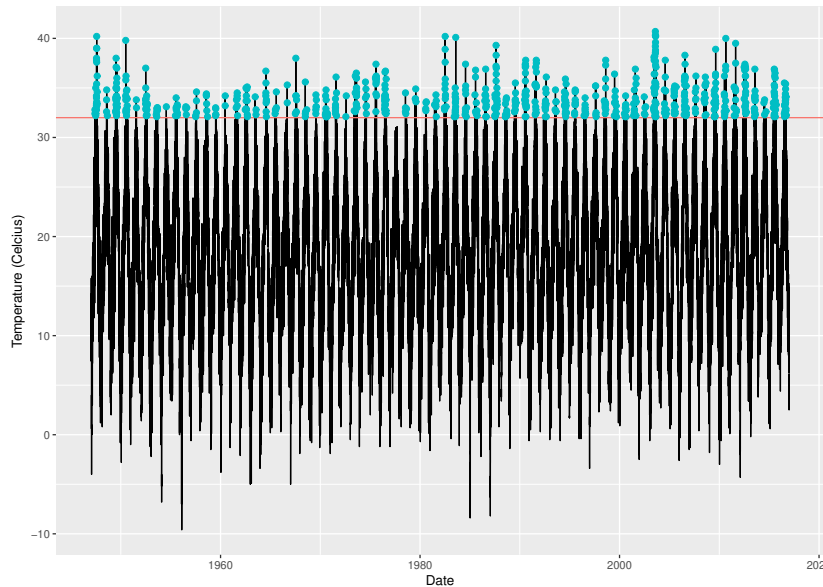
- Consider the 10–years return event $A = \{X > z_{10}\}$.
- This event **is expected** to occur 10 times in a century.
- However we have

$$\Pr(A \text{ not seen in the next 10 years}) = \begin{cases} \left(1 - \frac{1}{10}\right)^{10} \approx 0.35, & \theta = 1 \\ \left(1 - \frac{1}{10}\right)^{10\theta} = 0.90, & \theta = 0.1. \end{cases}$$

☞ When $\theta = 0.1$, these “expected 10 extremes” will tend to occur simultaneously leading to a higher probability of seeing none of them within the next 10 years.

Exceedances for stationary sequences

- 1. Block maxima
 - 2. Threshold exceedances
 - 3. Point process
 - 4. Non-stationary sequences
 - 5. Stationary sequences
- Stationary sequences
 $D(u_n)$ condition
GEV revisited
Extremal index
▷ Exceedances
Cluster maxima
Declustering



- Two approaches are possible:
 1. either you discard some observations to be closer to the i.i.d. assumption;
 2. or you take into account for such a serial dependence, e.g., assume a Markovian structure... **Not discussed here!**

Cluster maxima

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

▷ Cluster maxima

Declustering

- Because we usually use the MLE to fit the GPD // PPP, we have to use **cluster maxima only** for inference.
- Still the expected annual number of exceedances above z is

$$\Lambda\{(0, n_{\text{year}}^{-1}) \times (z, \infty)\} = \theta \left(1 + \xi \frac{z - \mu}{\sigma}\right)^{-1/\xi},$$

and the T -year return level y_p , $p = 1/T$, satisfies

$$T\theta \left(1 + \hat{\xi} \frac{y_p - \mu}{\sigma}\right)^{1/\hat{\xi}} = 1 \iff y_p = \mu + \frac{\sigma}{\hat{\xi}} \left\{(\theta T)^{\hat{\xi}} - 1\right\},$$

where the extremal index θ can be **estimated separately** by

$$\hat{\theta} = \frac{n_c}{n_u}, \quad n_c = \# \text{ clusters}, \quad n_u = \# \text{ exceedances above } u.$$

Cluster maxima

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

▷ Cluster maxima

Declustering

- Because we usually use the MLE to fit the GPD // PPP, we have to use **cluster maxima only** for inference.
- Still the expected annual number of exceedances above z is

$$\Lambda\{(0, n_{\text{year}}^{-1}) \times (z, \infty)\} = \theta \left(1 + \xi \frac{z - \mu}{\sigma}\right)^{-1/\xi},$$

and the T -year return level y_p , $p = 1/T$, satisfies

$$T\theta \left(1 + \hat{\xi} \frac{y_p - \mu}{\sigma}\right)^{1/\hat{\xi}} = 1 \iff y_p = \mu + \frac{\sigma}{\hat{\xi}} \left\{(\theta T)^{\hat{\xi}} - 1\right\},$$

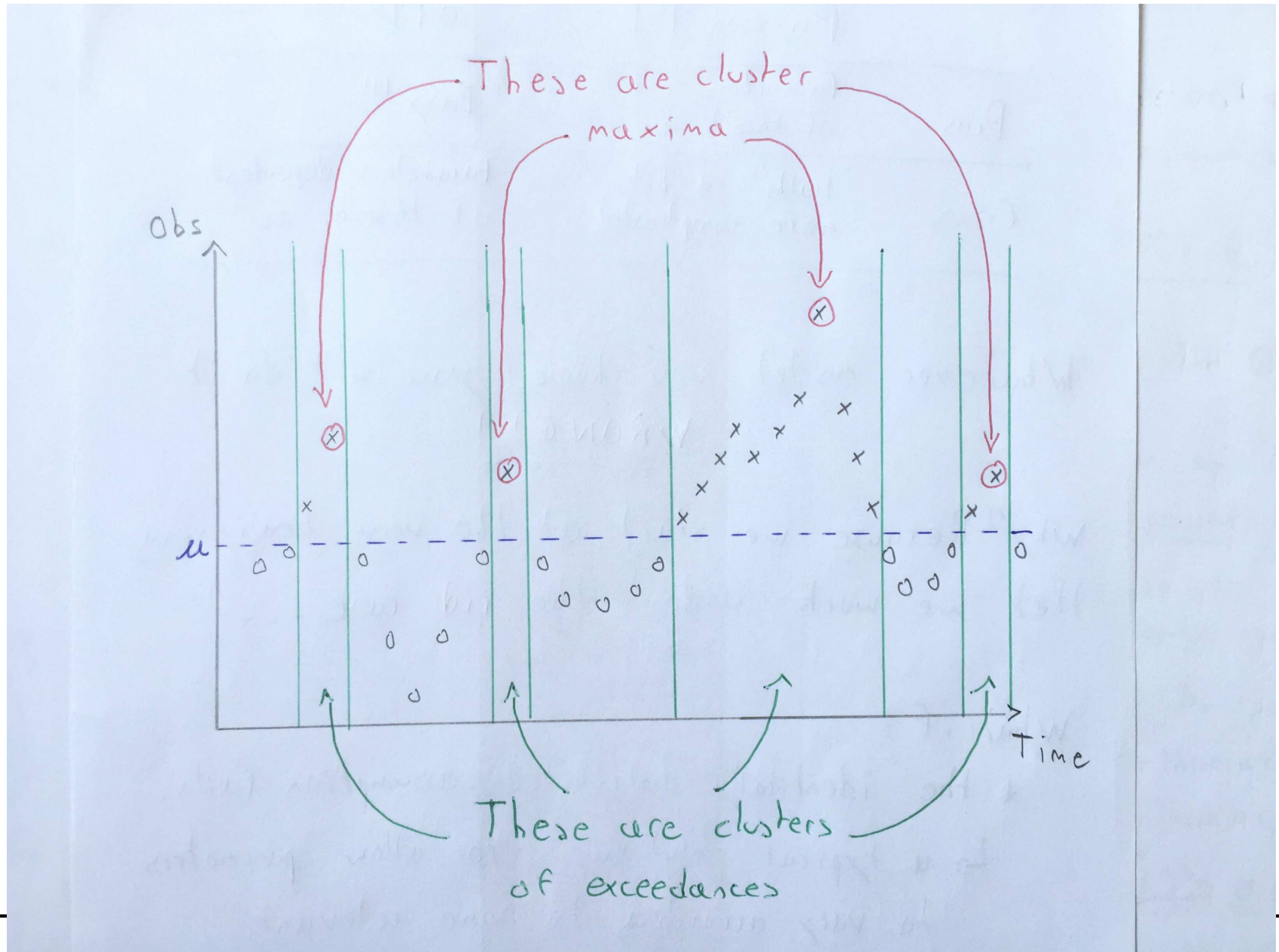
where the extremal index θ can be **estimated separately** by

$$\hat{\theta} = \frac{n_c}{n_u}, \quad n_c = \# \text{ clusters}, \quad n_u = \# \text{ exceedances above } u.$$

 We need to define cluster of exceedances!

Declustering: runs method

- 1. Block maxima
 - 2. Threshold exceedances
 - 3. Point process
 - 4. Non-stationary sequences
 - 5. Stationary sequences
- Stationary sequences
 $D(u_n)$ condition
GEV revisited
Extremal index
Exceedances
Cluster maxima
▷ Declustering



Declustering at Toulouse–Blagnac

```
> clusters(data, thresh, r, plot = TRUE)
```

1. Block maxima

2. Threshold exceedances

3. Point process

4. Non-stationary sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

Cluster maxima

▷ Declustering

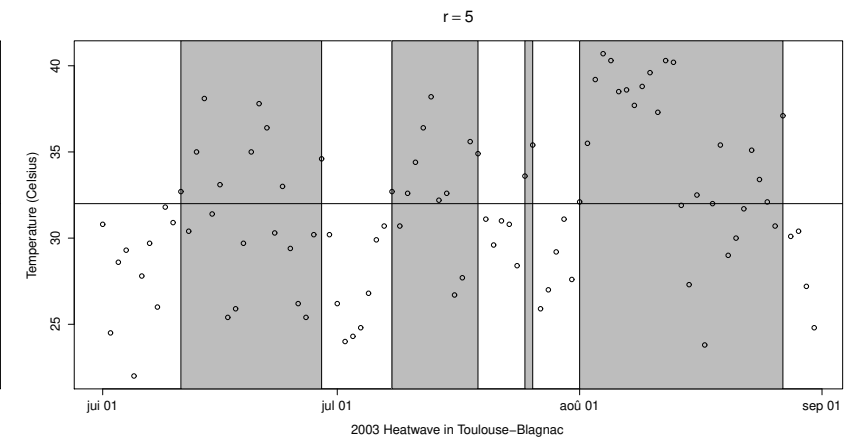
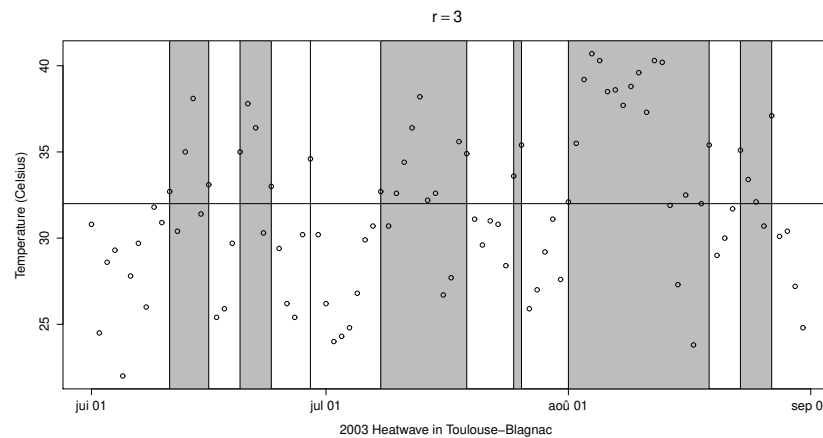
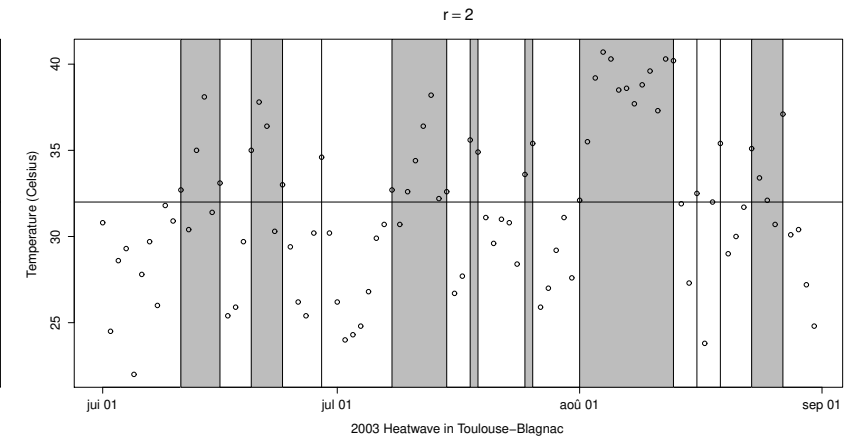
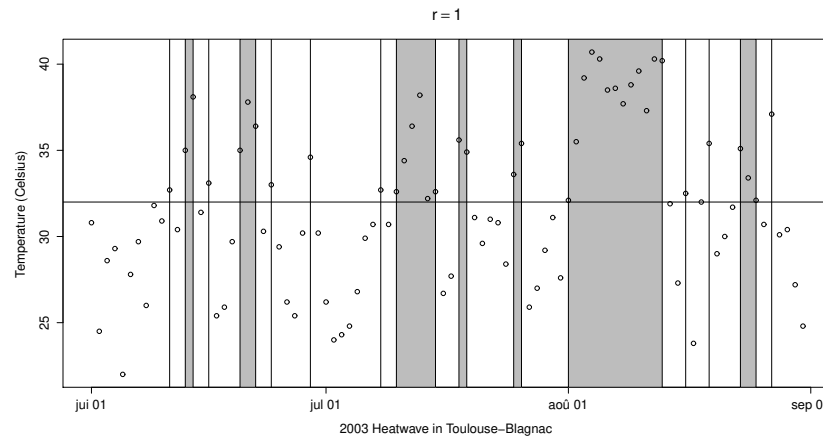


Illustration with the `evd` package

1. Block maxima

2. Threshold
exceedances

3. Point process

4. Non-stationary
sequences

5. Stationary sequences

Stationary sequences

$D(u_n)$ condition

GEV revisited

Extremal index

Exceedances

Cluster maxima

▷ Declustering

```
> fpot(df$Temperature, 32, "pp", npp = 365.25, cmax = TRUE, r = 3)
```

```
Call: fpot(x = df$Temperature, threshold = 32, model = "pp", npp = 365.25,  
          cmax = TRUE, r = 3)
```

```
Deviance: 807.4698
```

```
Threshold: 32
```

```
Number Above: 779
```

```
Proportion Above: 0.0305
```

```
Clustering Interval: 3
```

```
Number of Clusters: 330
```

```
Extremal Index: 0.4236
```

```
Estimates
```

```
      loc      scale      shape  
35.5823  1.8864 -0.2533
```

```
Standard Errors
```

```
      loc      scale      shape  
0.19606  0.08125  0.04456
```

- Here the extremal index estimate is $\hat{\theta} \approx 0.42$, i.e., clusters tends to be of size 2.5.
- ☞ It is typical, I think, for temperatures data but might be very different for, say, rainfall where $\theta \approx 1$.

	GEV	PPP	PPP ($r = 1$)	PPP ($r = 3$)	PPP ($r = 10$)
μ	35.2 (0.3)	36.6 (0.1)	35.8 (0.2)	35.6 (0.2)	34.6 (0.3)
σ	1.9 (0.2)	1.51 (0.07)	1.72 (0.07)	1.88 (0.08)	2.65 (0.16)
ξ	-0.16 (0.09)	-0.19 (0.03)	-0.23 (0.04)	-0.25 (0.04)	-0.35 (0.07)
y_{100}	41.3 (0.94)	41.1 (1.2)	40.3 (1.1)	40.1 (1.2)	39.6 (2.8)
θ	—	—	0.54	0.42	0.21